



Numerical simulations of star-disk magnetospheric interaction

Miljenko Čemeljić, 席門傑

Nicolaus Copernicus Astronomical Center of the Polish Academy
of Sciences, Warsaw, Poland

&

Academia Sinica Institute of Astronomy and Astrophysics,
Taipei, Taiwan



Outline

- Introduction
- ZEUS solutions and anomalous resistivity
- Analytical thin HD disk solution
- Numerical simulations in HD and MHD
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- Trends in the angular momentum flux
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- Long-lasting simulations
- Other geometries of magnetic field
- Light curve hiccups
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Introduction

- First numerical solution of (HD) accretion disk was by Prendergast & Burbidge (1968)
- Analytical solution was given by Shakura & Sunyaev (1973)
- ... (lots of good things, but mostly with 1D, vertically averaged models)
- In Kita (1995, PhD Thesis) and Kluźniak & Kita (2000, KK00) was given a solution of the thin HD polytropic disk in the full 3D. It was obtained by the method of asymptotic approximation with the disk thickness as a small parameter.
- In 2009, numerical simulations of star-disk magnetospheric interaction were done in 2D-axisymmetric simulations, by Romanova et al. (2009, 2013, with non-public code), Zanni & Ferreira (2009, 2013, with the publicly available PLUTO code).
- Development of disk simulations went in the direction of MRI in the disk (Flock et al. 2012) or radiative transfer simulations.
- In Čemeljić (2019), A&A, 624, A31, I repeated the Zanni et al. (2009, 2013) 2D axisymmetric viscous & resistive MHD simulations with PLUTO (ver. 4.1), and went on to a parameter study, to investigate the influence of different parameters.

Status when I started with ZEUS star-disk simulations

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Table 1

In Many Resistive MHD Simulations Performed To Date, Assumptions for the Initial Conditions Vary Significantly and the Duration of Simulations is Very Different

	Ω_*	Corona	$\kappa = \rho_d / \rho_c$	T_{\max} / T_0 (days)	Resistive	Viscous
Hayashi et al. (1996)	Non-rotating	Non-rotating	10^3	5	Yes	No
Hirose et al. (1997)	Non-rotating	Rotating	10^4	16.5	Yes	No
Miller & Stone (1997)	Slow	Rotating different than disk Solid body rotation Corotating with star at R_{cor}	10^2	0.3	Yes	No
Goodson et al. (1999)	Fast	Rotating	10^4	100	Yes	No
Romanova et al. (2002)	Slow	Corotating with star for $R \leq R_{\text{cor}}$, else with disk	10^2	100	No	Yes
Küker et al. (2003)	Slow	Not in hydrostatic balance, non-rotating	10^3	1000	Yes	Yes
Ustyugova et al. (2006)	Fast	Corotating with star for $R \leq R_{\text{cor}}$, else with disk	10^3	2000	Yes	Yes
Romanova et al. (2009)	Fast and slow	Corotating with star for $R \leq R_{\text{cor}}$, else with disk	10^4	2000	Yes	Yes
M. Čemeljić et al. (present paper)	Slow	Corotating with star for $R \leq R_{\text{cor}}$, else with disk	10^4	1500	Yes	No

Notes. We list some of the important works to put our work in context. In the second column, “fast” stellar rotation means that the corotation radius is smaller than the disk truncation radius, $R_{\text{cor}} < R_t$, and “slow” rotation means that $R_{\text{cor}} > R_t$. The disk is rotating in all the cases. The columns about physical resistivity and viscosity specify only if the option is included in the code at all; for where it is really effective, reader should check the related publication. When present, viscosity is important only in the disk.

ZEUS simulations results-microejections

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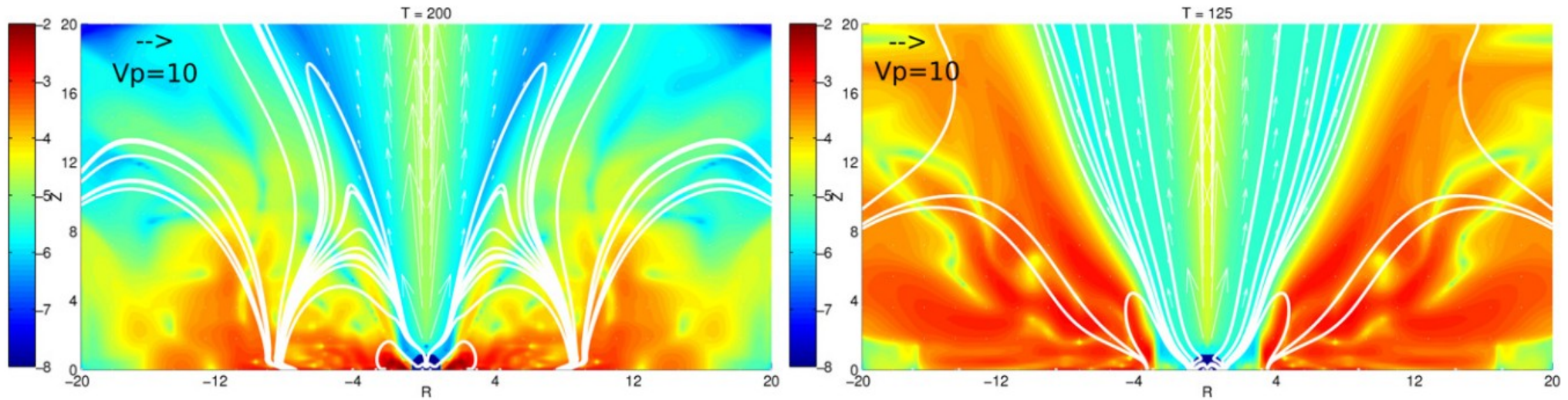
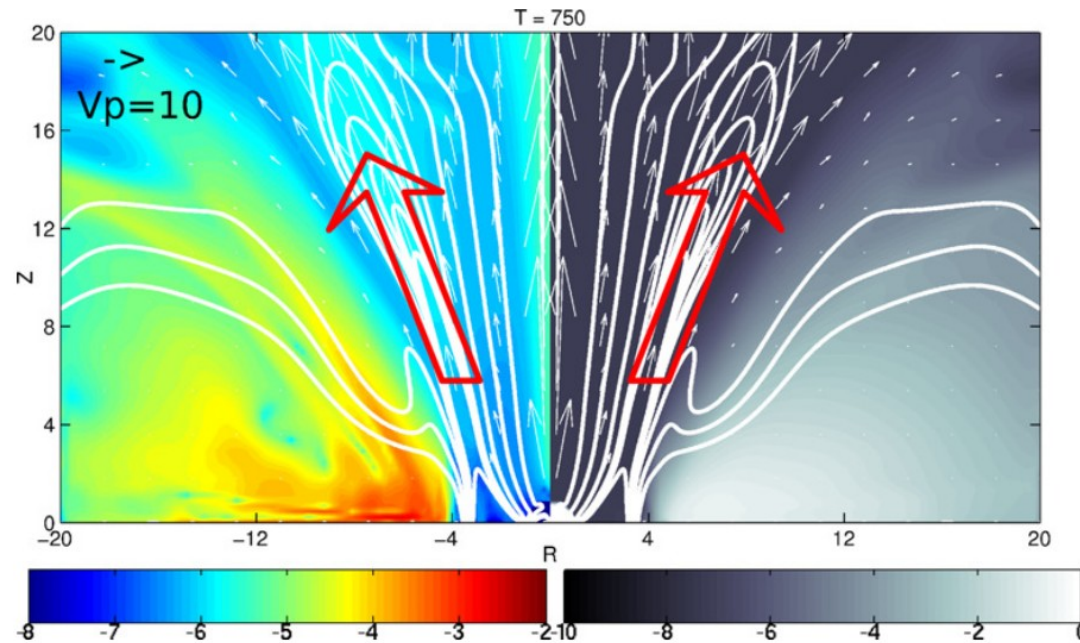


Figure 5. Mass flux ρv for the case with medium magnetic field in simulation S1a is shown in the left panel, and in simulation S1b, with larger magnetic field, in



simulation S2. The left half of each panel shows the poloidal mass flux ρv_p , and the right half shows the density.

ZEUS results-effects of anomalous resistivity

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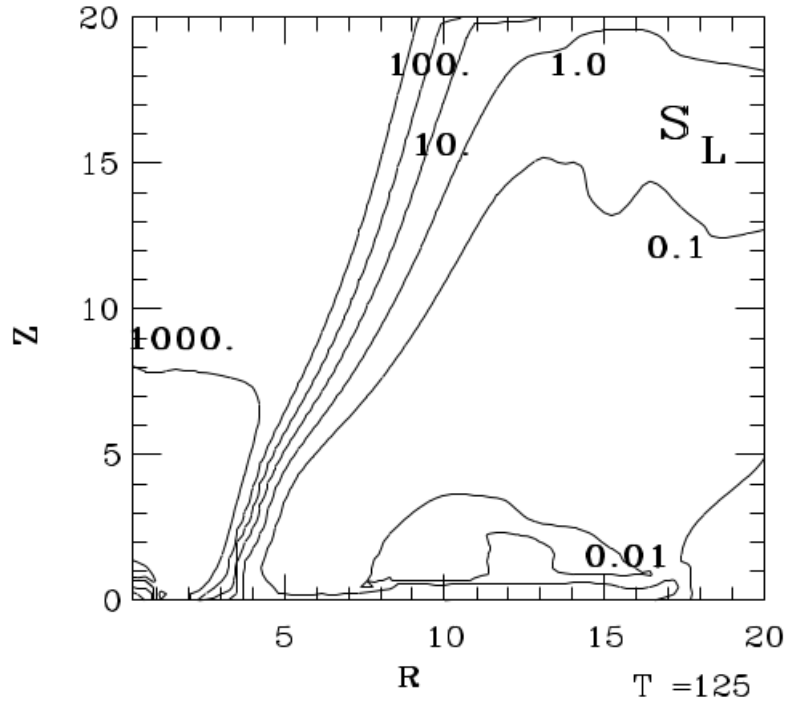


Figure 23. Isocontours of the Lundquist number S_L in S1b, at $T = 125$. Values of S_L for some isocontours are labeled on the plot.

The electrical resistivity η is defined through the electric conductivity σ as $\eta = c^2/4\pi\sigma$, where c is the speed of light. The ratio of the advection and diffusion terms in the induction Equation (3) is the magnetic Reynolds number $Rm = VL/\eta$, where V and L stand for the characteristic speed and distance, respectively. The characteristic speed in our problem is the Alfvén speed $v_A = B/(4\pi\rho)^{1/2}$, which defines the Lundquist number⁴ S_L :

$$S_L = \frac{v_A L}{\eta}. \quad (18)$$

To explain the physical processes, the accretion disk requires an enhanced, *anomalous* level of resistivity, which is much larger

Another number that we find to indicate where the launching is possible from is the Elsässer number. It is defined by the ratio of the Z-component of the Alfvén velocity and $\eta\Omega_K$ (see Salmeron et al. 2007 and references therein):

$$\Lambda \equiv \frac{V_{AZ}^2}{\eta\Omega_K} > 1. \quad (21)$$

In some systems, when the flow is mainly in the Z-direction, Λ can be similar or equal to the Lundquist number S_L or the magnetic Reynolds number Rm , but, in general, they are different because the velocity of the outflow differs from the Alfvén velocity.

In Figure 24, we plot the Elsässer number $\Lambda > 1$ in simulations S1b and S2. We observe that $\Lambda \geq 1$ is valid only in the magnetosphere above the disk. For a small magnetic field of

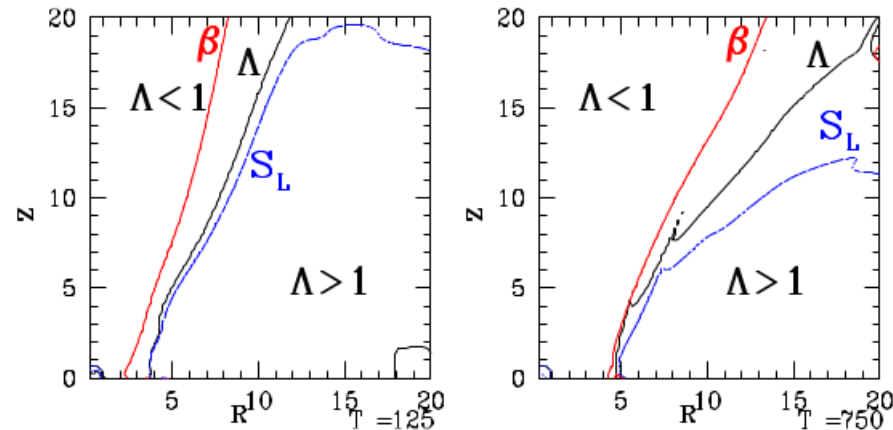


Figure 24. Elsässer number Λ is shown by the thick (black) solid line at $T = 125$ and $T = 750$ in simulations S1b and S2, in the left and right panels, respectively. Above the line in the computational box where magnetic pressure equals matter pressure ($\beta = 1$), and where the Elsässer number Λ equals unity (red solid line), launching of a flow of matter is possible. Below those lines, the

Kluźniak-Kita thin disk analytical solutions

Initial conditions are HD disk and a hydrostatic corona. Examples from derivation:

Equation of continuity:

$$\frac{\epsilon}{r} \frac{\partial}{\partial r} (r \rho v_r) + \frac{\partial}{\partial z} (\rho v_z) = 0 \quad (1)$$

Order ϵ^0 :

$$\frac{\partial}{\partial z} (\rho_0 v_{z0}) = 0 \Rightarrow v_{z0} = 0 \quad (2)$$

Order ϵ^1 :

$$\frac{1}{r} \frac{\partial}{\partial r} (r \rho_0 v_{r0}) + \frac{\partial}{\partial z} (\rho_0 v_{z1}) = 0 \quad (3)$$

From the argumentation presented below, for the first order in ϵ of the radial momentum, we have $v_{r0} = 0$, so that here we have $\partial_z(\rho_0 v_{z1}) = 0 \Rightarrow \rho_0 v_{z1} = \text{const}$ along z . Since v_z is odd with respect to z , at the disk equatorial plane it is $\rho_0 v_{z1} = 0$. Since it does not depend on z , and $\rho_0 \neq 0$, we conclude that $v_{z1} = 0$.

Order ϵ^2 :

$$\frac{1}{r} \frac{\partial}{\partial r} (r \rho_0 v_{r1}) + \frac{\partial}{\partial z} (\rho_0 v_{z2}) = 0 \quad (4)$$

Vertical momentum:

$$\begin{aligned} \epsilon v_r \frac{\partial v_z}{\partial r} + v_z \frac{\partial v_z}{\partial z} = & -\frac{z}{r^3} \left[1 + \epsilon^2 \left(\frac{z}{r} \right)^2 \right]^{-3/2} \\ -n \frac{\partial c_s^2}{\partial z} + \frac{2}{\gamma \tilde{\beta}} \frac{1}{\rho} \left(\epsilon B_r \frac{\partial B_z}{\partial r} + B_z \frac{\partial B_z}{\partial z} \right) - \frac{1}{\gamma \tilde{\beta}} \frac{1}{\rho} \frac{\partial B^2}{\partial z} \\ & + \frac{2}{\rho} \frac{\partial}{\partial z} \left(\eta \frac{\partial v_z}{\partial z} \right) + \frac{\epsilon^2}{\rho r} \frac{\partial}{\partial r} \left(r \eta \frac{\partial v_z}{\partial r} \right) \\ & - \frac{2}{3} \frac{\epsilon}{\rho} \frac{\partial}{\partial z} \left(\frac{\eta}{r} \frac{\partial}{\partial r} (r v_r) \right) - \frac{2}{3\rho} \frac{\partial}{\partial z} \left(\eta \frac{\partial v_z}{\partial z} \right) \\ & + \frac{\epsilon}{\rho r} \frac{\partial}{\partial r} \left(\eta r \frac{\partial v_r}{\partial z} \right) \end{aligned} \quad (17)$$

Order ϵ^0 :

$$0 = -\frac{z}{r^3} - n \frac{\partial c_{s0}^2}{\partial z} - \frac{1}{\gamma \tilde{\beta}} \frac{1}{\rho_0} \frac{\partial B_0^2}{\partial z} \quad (18)$$

Since we had $\partial B_{r0}/\partial z = \partial B_{z0}/\partial z = \partial B_{\varphi 0}/\partial z = 0$, we have $\partial B_0/\partial z = 0$, i.e. $B_0 = f(r)$. We have then

$$\frac{z}{r^3} = -n \frac{\partial c_{s0}^2}{\partial z}, \quad (19)$$

which is the vertical hydrostatic equilibrium equation, with the solution in the case of $n = 3/2$:

$$c_{s0} = \sqrt{\frac{h^2 - z^2}{3r^3}}, \quad \rho_0 = \left(\frac{h^2 - z^2}{5r^3} \right)^{3/2}, \quad (20)$$

where h is the semi-thickness of the disk. This also gives us the pressure relation $P = \rho_0^{5/3} = [(h^2 - z^2)/5r^3]^{5/2}$ (Hoshi 1977; Kluźniak & Kita 2000).

Numerical setup

- I perform simulations of a rotating thin accretion disk, which reach a quasi-stationary state.

- Ohmic and viscous heating in the energy equation are neglected, assuming that all the heat is radiated away.

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{u}) = 0$$

$$\frac{\partial \rho \mathbf{u}}{\partial t} + \nabla \cdot \left[\rho \mathbf{u} \mathbf{u} + \left(P + \frac{\mathbf{B} \cdot \mathbf{B}}{8\pi} \right) \mathbf{I} - \frac{\mathbf{B} \mathbf{B}}{4\pi} - \boldsymbol{\tau} \right] = \rho \mathbf{g}$$

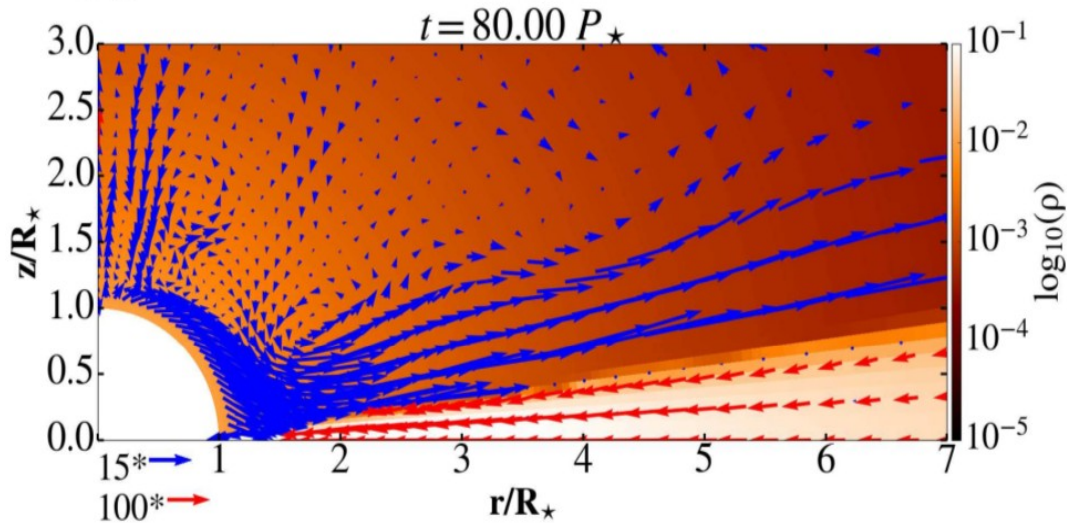
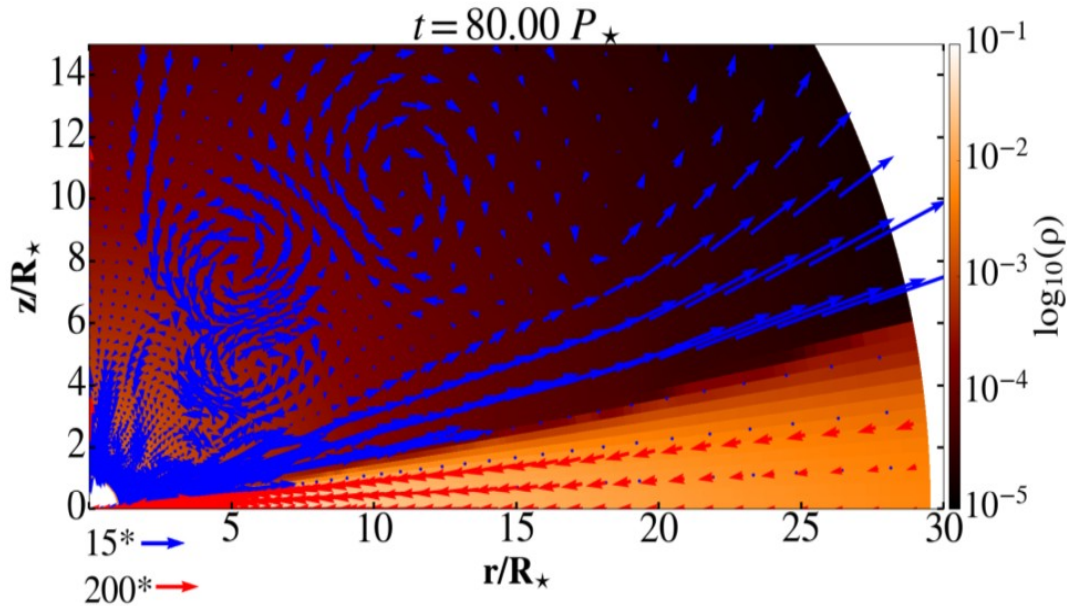
- Viscosity and resistivity are still included, in the equation of motion and in the induction equation.

$$\frac{\partial E}{\partial t} + \nabla \cdot \left[\left(E + P + \frac{\mathbf{B} \cdot \mathbf{B}}{8\pi} \right) \mathbf{u} - \frac{(\mathbf{u} \cdot \mathbf{B}) \mathbf{B}}{4\pi} \right] + \nabla \cdot [\eta_m \mathbf{J} \times \mathbf{B} / 4\pi - \mathbf{u} \cdot \boldsymbol{\tau}] = \rho \mathbf{g} \cdot \mathbf{u} - \Lambda_{\text{cool}}$$

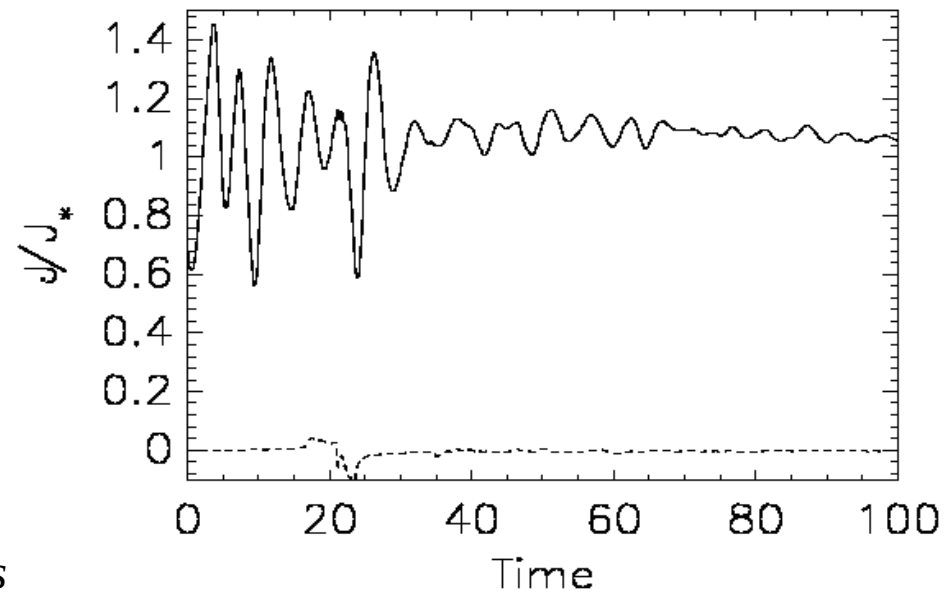
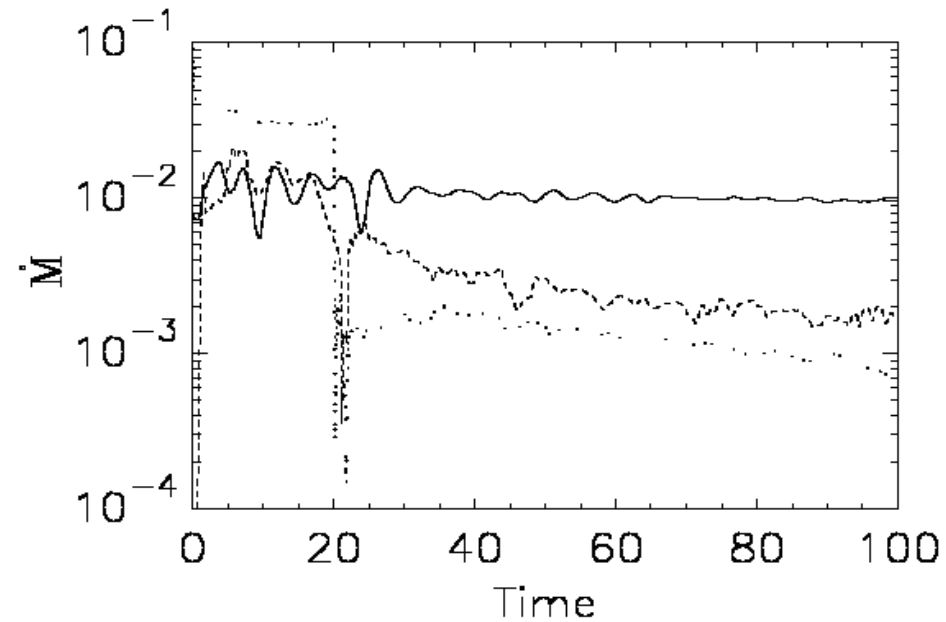
$$\frac{\partial \mathbf{B}}{\partial t} + \nabla \times (\mathbf{B} \times \mathbf{u} + \eta_m \mathbf{J}) = 0.$$

- Code used is PLUTO (v.4.1) by Mignone et al. (2007).

Hydro-dynamic star-disk analytical solutions and simulations

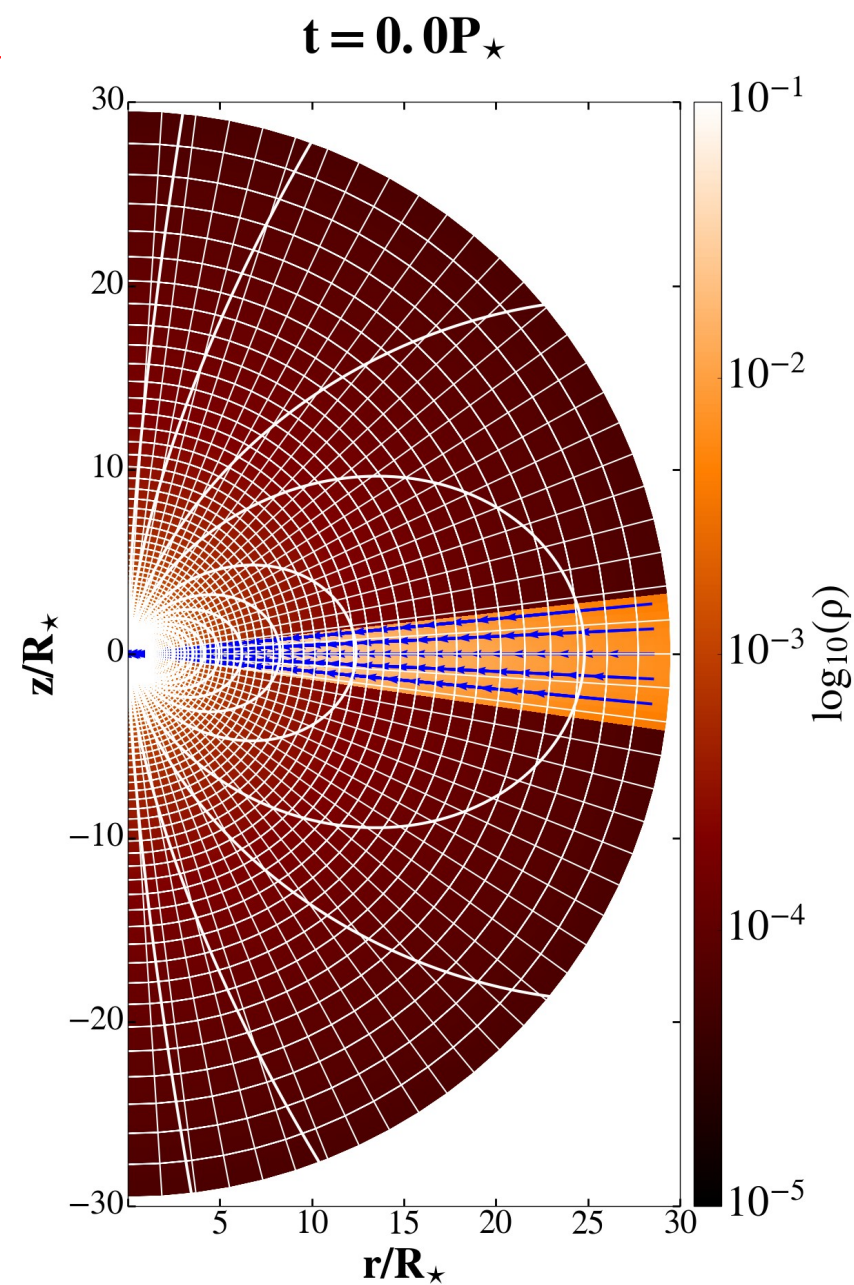
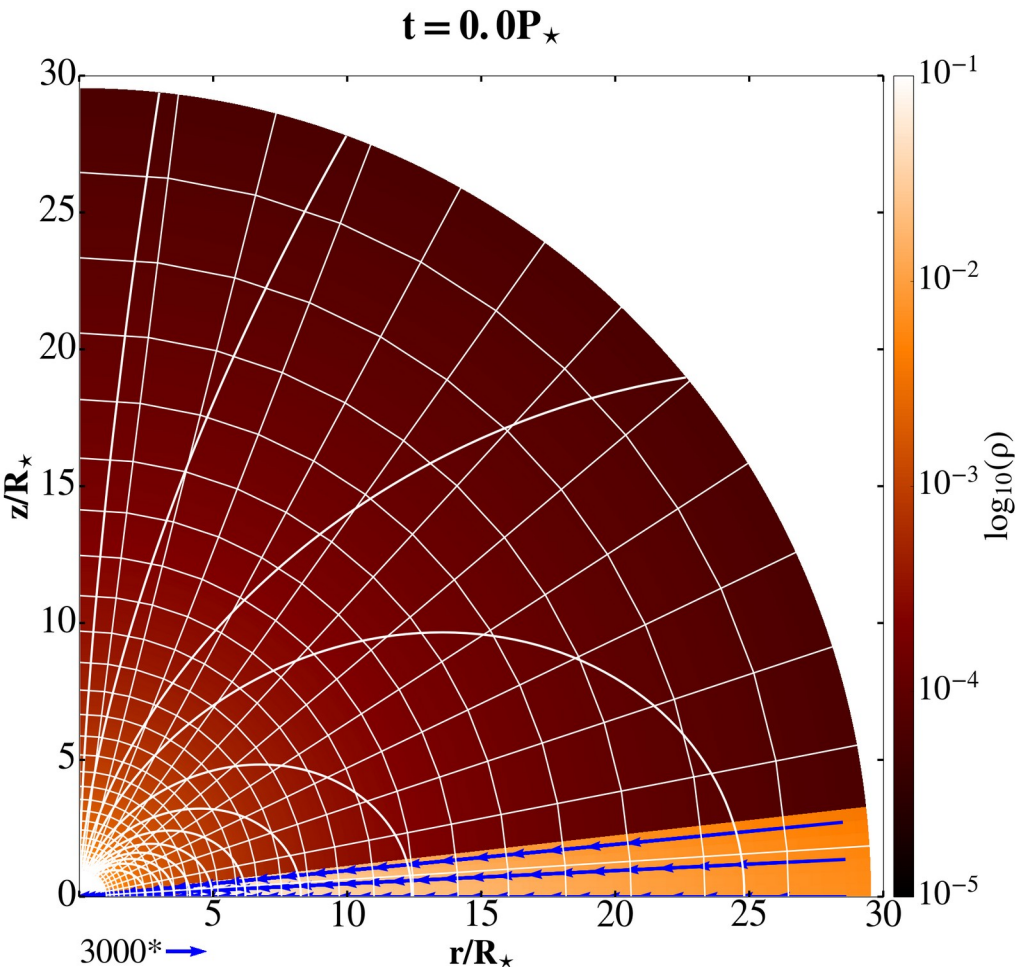


Computational box and a zoom closer to the star after 80 stellar rotations. In color is shown the density, and vectors show velocity, with the different normalization in the disk and stellar wind.



Time dependence of the mass and angular momentum fluxes in the various components in our simulations.

Star-disk simulations with magnetic field



- We add the magnetic field to the HD solution
- Stellar surface is a rotating boundary condition at the origin of the spherical computational domain. We assume the star to be a magnetized rotator. The initially non-rotating corona is in a hydrostatic balance.

Star-disk simulations with $\alpha_v=1$

Table 1. The parameters in our study presented in the “Atlas”: the stellar angular velocity Ω_\star , stellar dipole magnetic field strength B_\star , and the magnetic Prandtl number P_m -for which we also table the values of corresponding resistivity coefficient α_m . We show also the stellar rotation period, and corotation radius in young stellar object (YSO) cases.

$\Omega_\star/\Omega_{\text{br}}$	$B_\star(\text{G})$	P_m	α_m	$P_\star(\text{days})$	$R_{\text{cor}}(R_\star)$
0.05	250	6.7	0.1	9.2	7.37
0.1	500	1.67	0.4	4.6	4.64
0.15	750	0.95	0.7	3.1	3.54
0.2	1000	0.67	1.0	2.3	2.92

- Prandtl magnetic number:

$$P_m = \frac{2}{3} \frac{\alpha_v}{\alpha_m}$$

Star-disk simulations parameter space

Table 1. We performed 64 star-disk magnetospheric interaction simulations in a setup detailed in Čemeljić (2019). There are all together 64 runs with all the combinations of parameters as listed in the table. The magnetic Prandtl number $P_m = \frac{2}{3}\alpha_v/\alpha_m$ is also listed – in all the cases the anomalous viscosity parameter is $\alpha_v = 1$. The four simulations shown in Fig. 1 are highlighted with boxed bold letters.

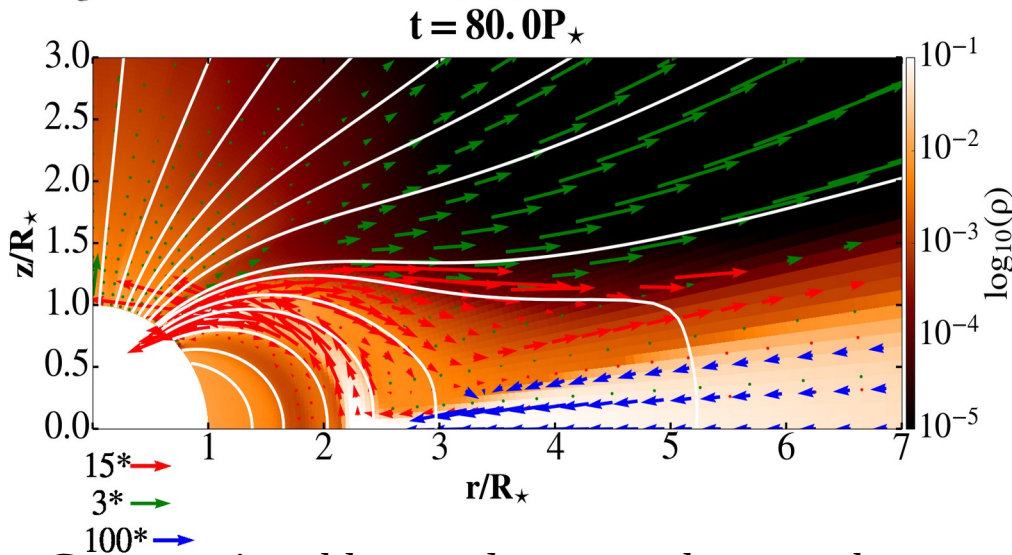
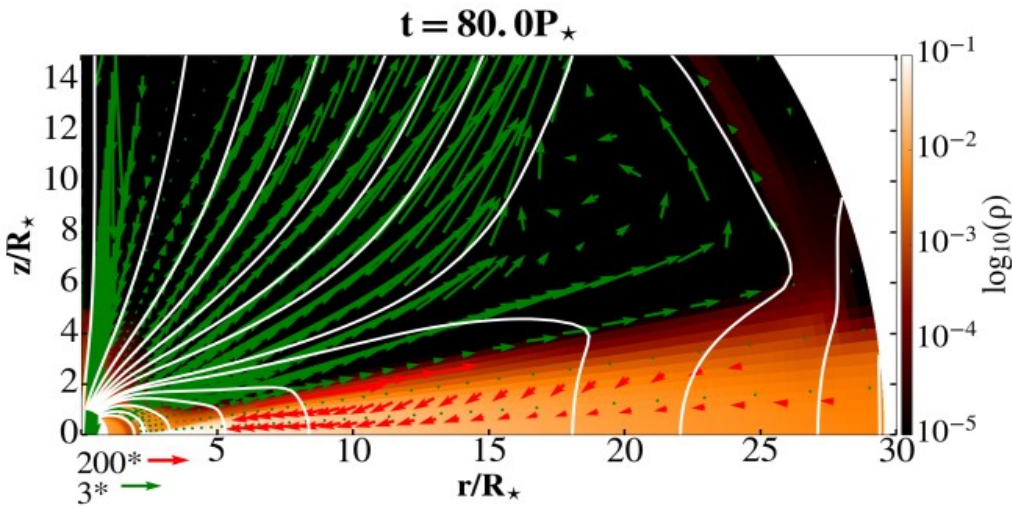
$\alpha_m =$	0.1	0.4	0.7	1
$P_m =$	6.7	1.67	0.95	0.67
Ω_\star/Ω_{br}				
$B_\star=250$ G				
0.05	a1	a2	a3	a4
0.1	a5	a6	a7	a8
0.15	a9	a10	a11	a12
0.2	a13	a14	a15	a16
$B_\star=500$ G				
0.05	b1	b2	b3	b4
0.1	b5	b6	b7	b8
0.15	b9	b10	b11	b12
0.2	b13	b14	b15	b16
$B_\star=750$ G				
0.05	c1	c2	c3	c4
0.1	c5	c6	c7	c8
0.15	c9	c10	c11	c12
0.2	c13	c14	c15	c16
$B_\star=1000$ G				
0.05	d1	d2	d3	d4
0.1	d5	d6	d7	d8
0.15	d9	d10	d11	d12
0.2	d13	d14	d15	d16

I did a systematic study with magnetic star-disk numerical simulations in 64 points in parameter space, for a slowly rotating star.

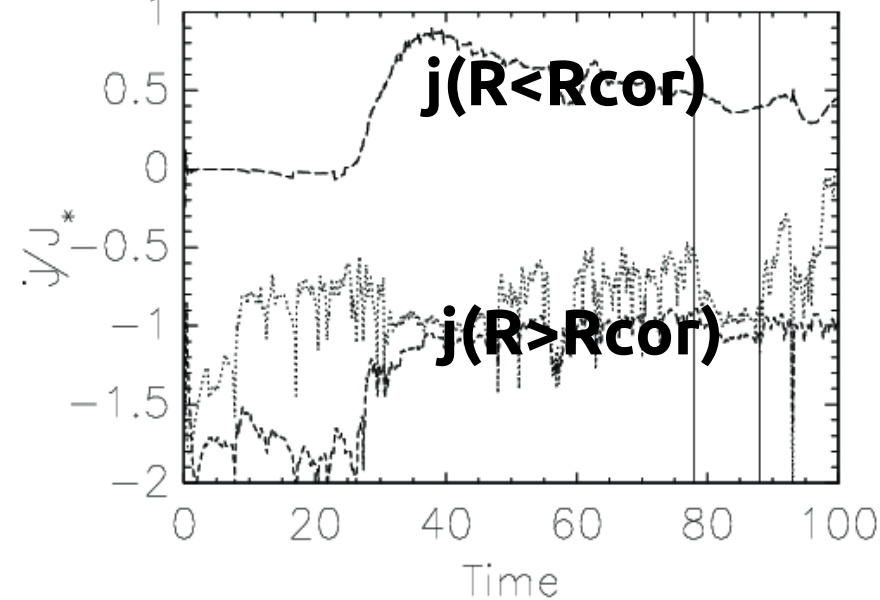
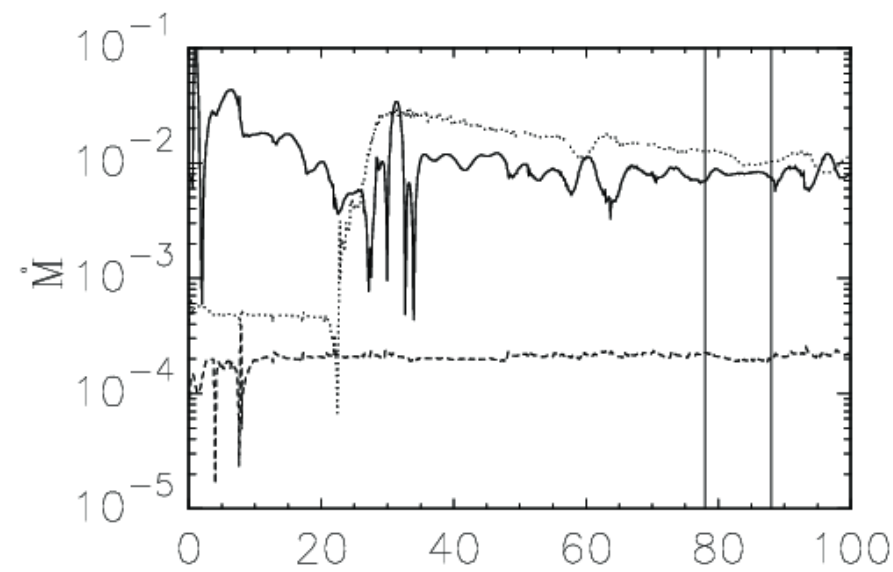
With PhD students in CAMK and in Taiwan, and with summer students, we continue this work, to go to the other parts of the parameter space and other geometries of magnetic field.

Sure, it would be better done in full 3D, but 2D axisymmetric results will be faster available, and will be good to have later for a comparison with 3D.

Star-disk magnetospheric interaction (SDMI) simulations

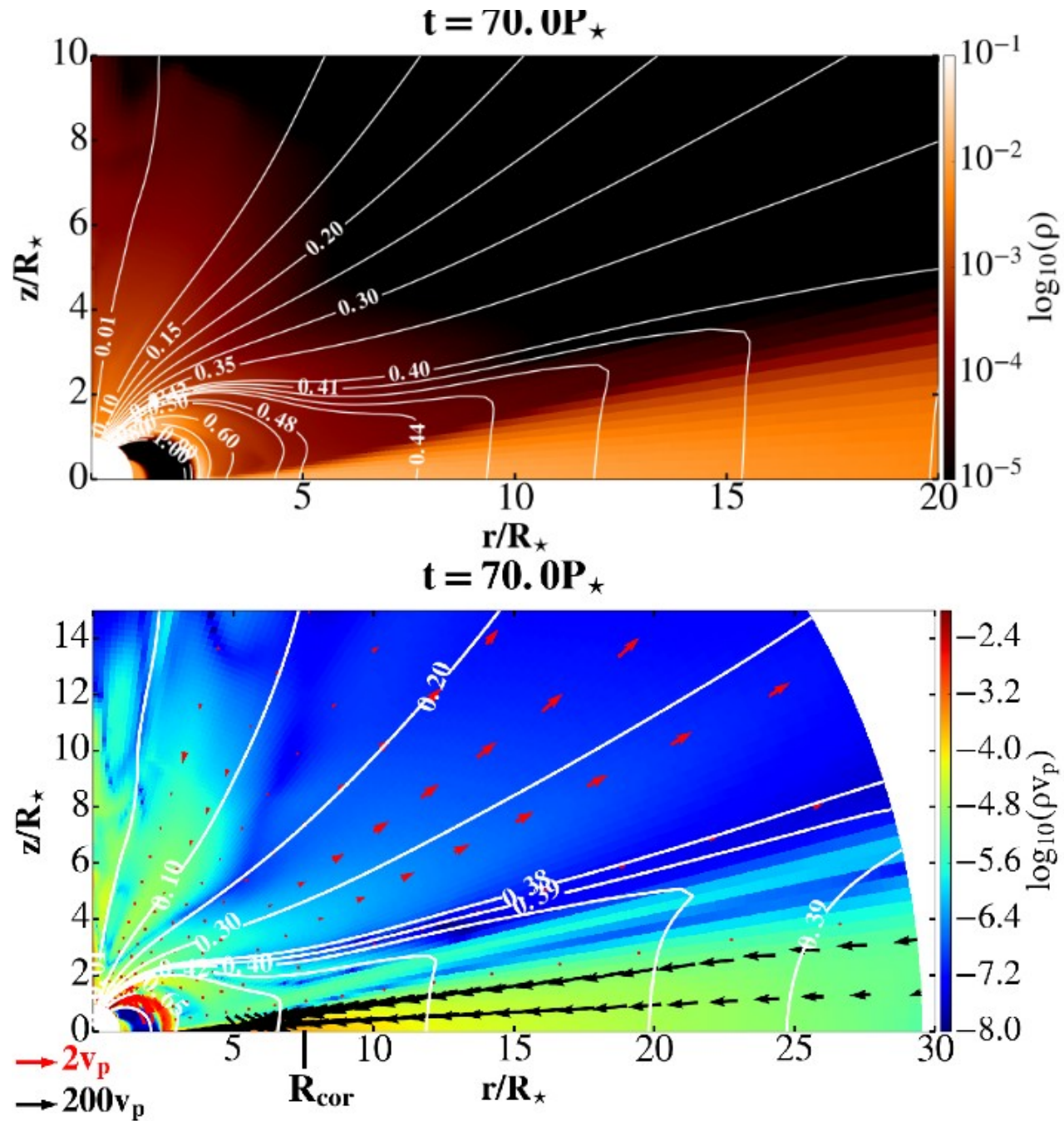


Computational box and a zoom closer to the star after 80 stellar rotations, to visualize the accretion column and the magnetic field lines (white solid lines), connected to the disk beyond the corotation radius $R_{\text{cor}} = 2.92 R_{\text{s}}$. In color is shown the density, and vectors show velocity, with the different normalization in the disk, column and stellar wind.



Time dependence of the mass and angular momentum fluxes in the various components in our simulations with marked the time interval in which the average for the quasi-stationarity is computed.

Example of a solution with 500 Gauss



Types of solutions in “Atlas”

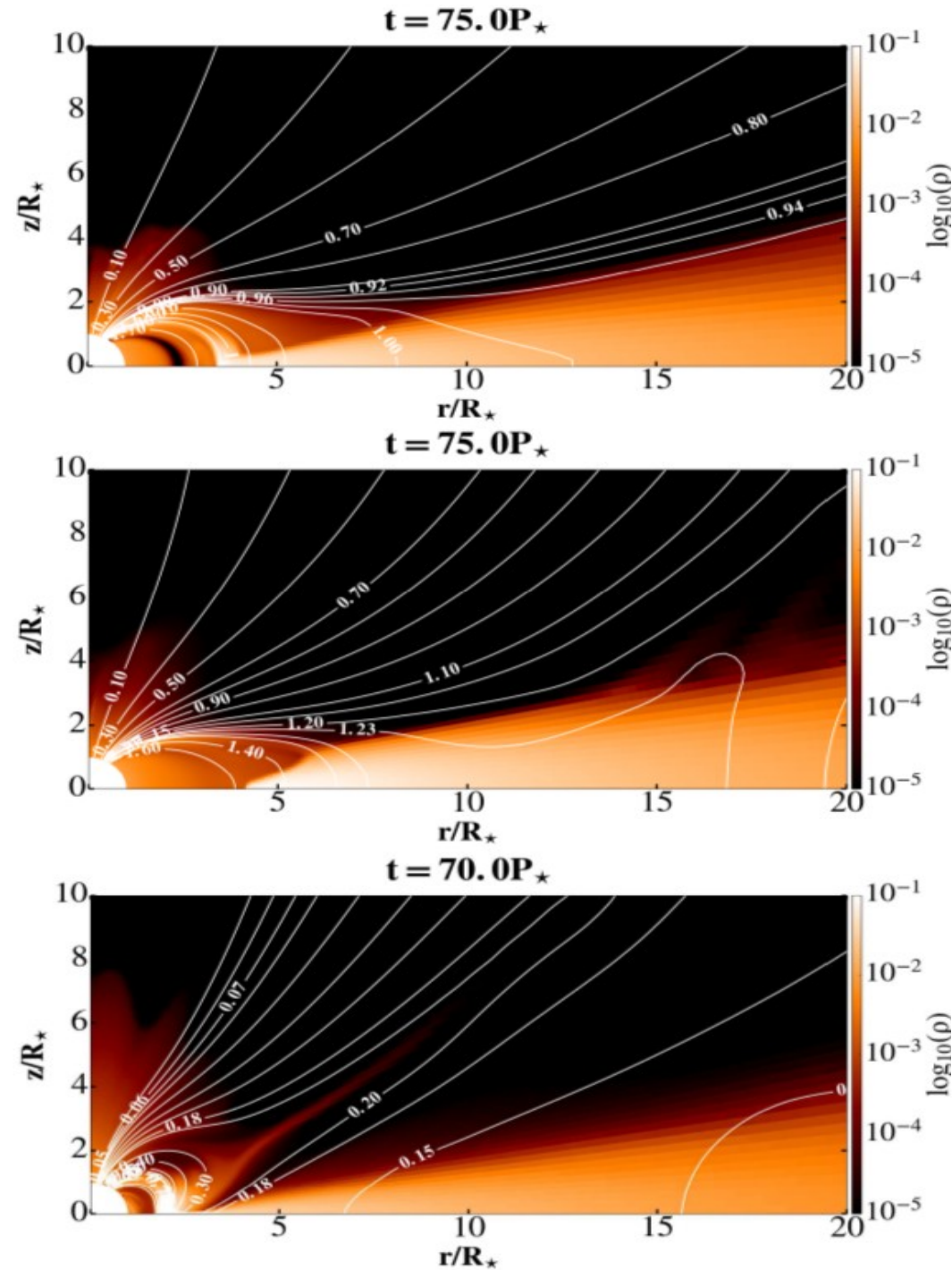
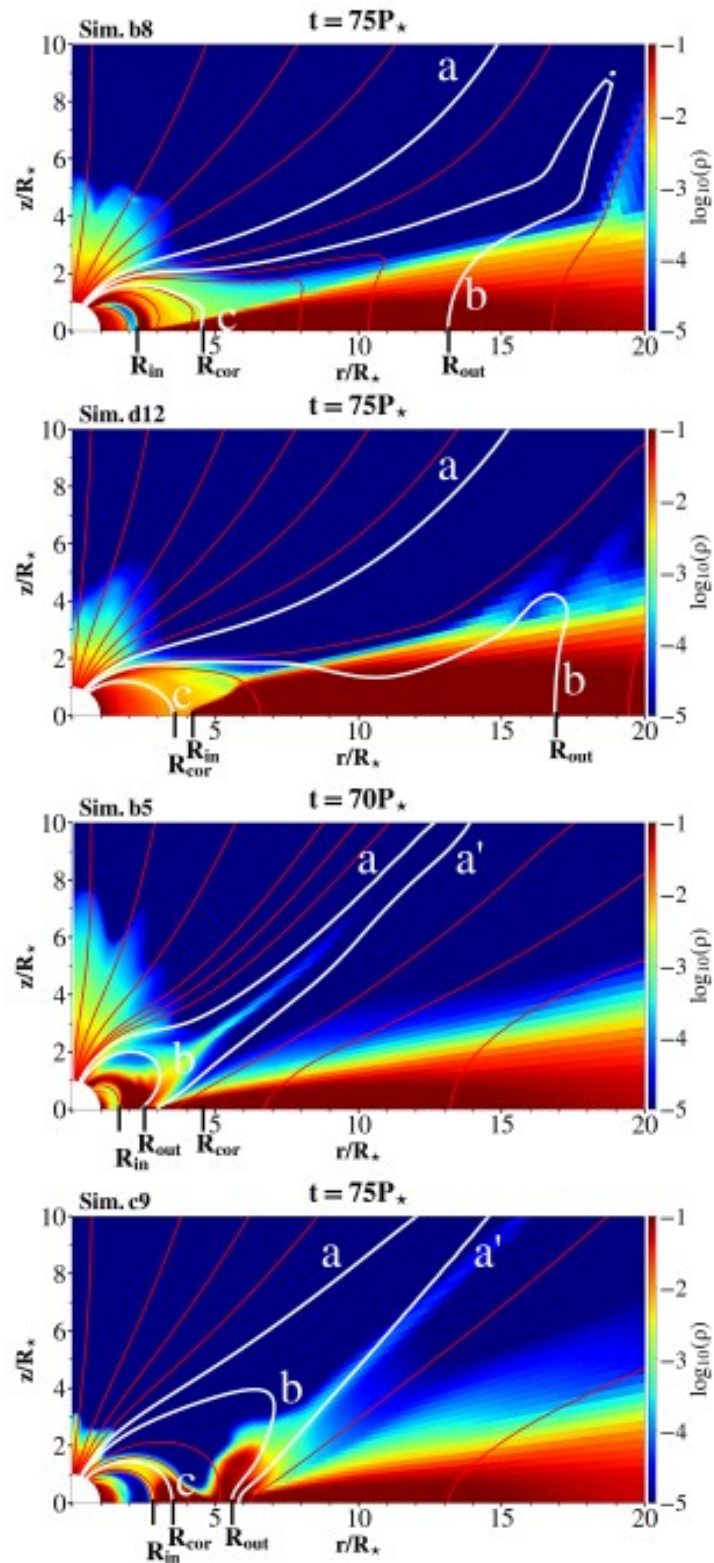


Table 2. Parameter space in the simulations, with an “Atlas” of solutions, where the geometry of the flow components in each case is labeled with D for disk, DC for disk+column, and DCE for disk+column+ejection.

$\alpha_m =$	0.1	0.4	0.7	1
Ω_\star/Ω_{br}				
$B_\star = 250 \text{ G}$				
0.05	DCE	DC	DC	DC
0.1	DCE	DC	DC	DC
0.15	DCE	DC	DC	DC
0.2	DCE	DC	DC	DC
$B_\star = 500 \text{ G}$				
0.05	DCE	DC	DC	DC
0.1	DCE	DC	DC	DC
0.15	DCE	DC	DC	DC
0.2	DCE	DC	DC	DC
$B_\star = 750 \text{ G}$				
0.05	DCE	DC	DC	DC
0.1	DCE	DC	DC	DC
0.15	DCE	DC	DC	DC
0.2	DCE	DC	DC	DC
$B_\star = 1000 \text{ G}$				
0.05	DCE	DC	DC	DC
0.1	DCE	DC	DC	DC
0.15	DCE	D	D	D
0.2	DCE	D	D	D

- Three different cases of geometry in our results: top and middle panels $B=1 \text{ kG}$ and $\alpha_m=1$, in the cases with $\Omega_s=0.1$ and $\Omega_s=0.15$, bottom panel $B=0.5 \text{ kG}$, $\alpha_m=0.1$, $\Omega_s=0.1$.

Types of solutions in “Atlas”



- 4 different cases if we consider the position of R_{cor} in the case with conical outflow.
- In general, faster stellar rotation prevents the accretion column formation.
- In the bottom panels resistivity $\alpha_m=0.1$ and $\Omega_s=0.1$, a conical outflow is formed.

Comparison of SDMI simulations with increasing mag. field

M. Čemeljić et al.: Magnetically threaded accretion discs

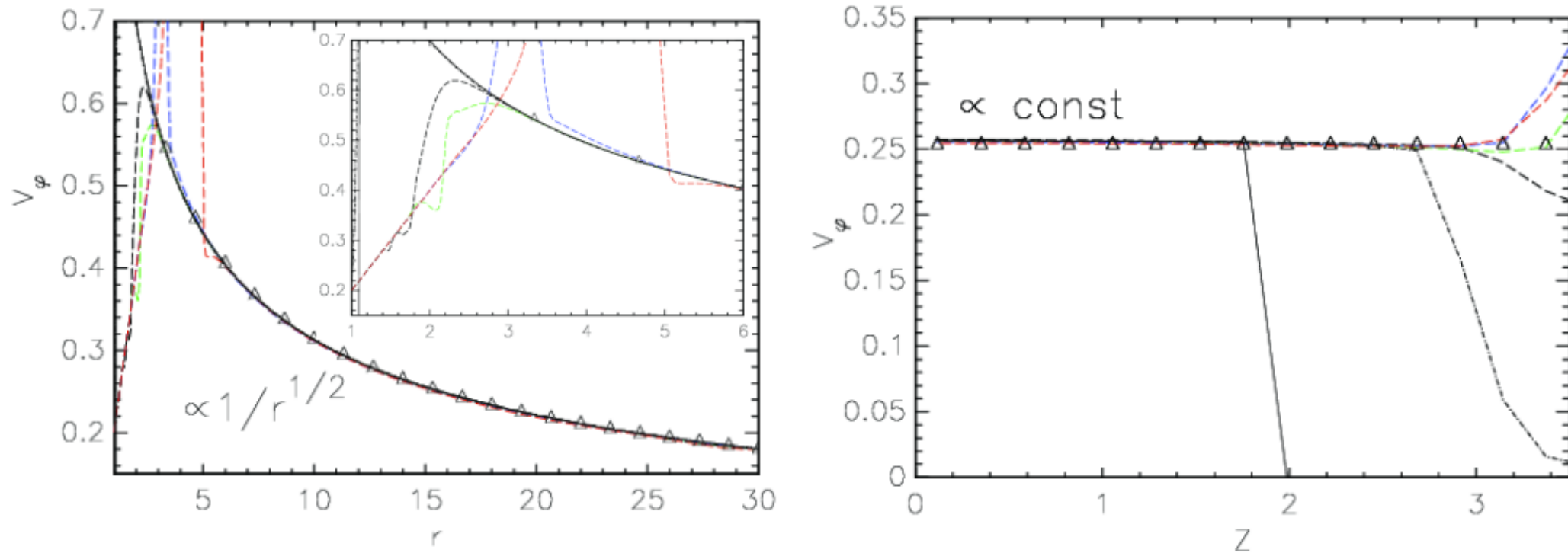


Fig. 2. The azimuthal velocity of thin discs from our simulations with $\Omega = 0.2 \Omega_{\text{ms}}$. As expected from theory, it closely follows the Keplerian curve and is uniform on cylinders (with corrections of order z^2/r^2). The disc-corona interface is at $z \approx 2$. In this and later figures, shown are values in the initial set-up (thin solid line) with the quasi-stationary solutions in the numerical simulations in the HD (dot-dashed line) and the MHD (long-dashed line) cases. In black, green, blue and red colors are the results in the MHD cases with the stellar magnetic field strength $(0.35, 0.7, 1.05, 1.4)B_0$, respectively. The closest match to the $0.7B_0$ case is depicted with triangle symbols. *Left panel:* radial dependence along the midplane, just above $\theta=90^\circ$. Insert shows a zoom into the vicinity of the stellar surface. *Right panel:* the profiles along a vertical line at $r=15R_\star$. The thin solid line in the right panel, sloping down at $z \approx 2$, indicates v_ϕ in the initial set-up.

Comparison of SDMI simulations with increasing mag. field

M. Čemeljić et al.: Magnetically threaded accretion discs

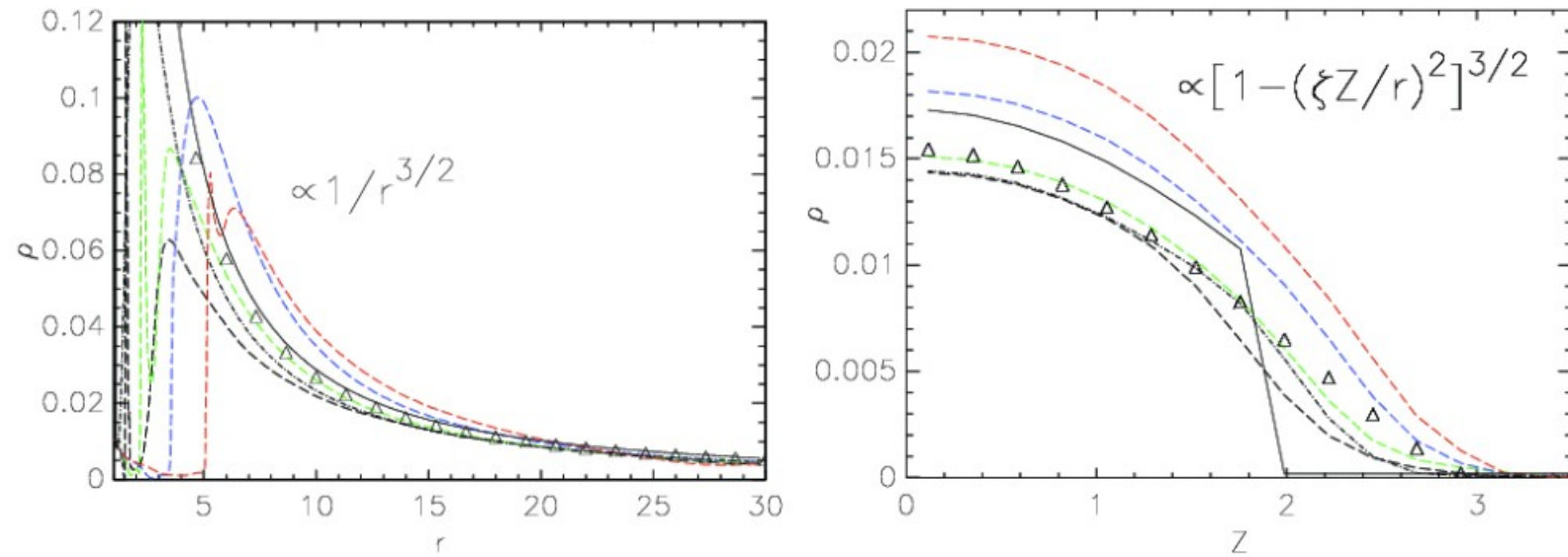


Fig. 3. Comparison of the matter density *Left panel*: radial dependence along the midplane, just above $\theta=90^\circ$. *Right panel*: the profiles along the vertical line at $r=15R_*$. The legend is the same as in Fig. 2.

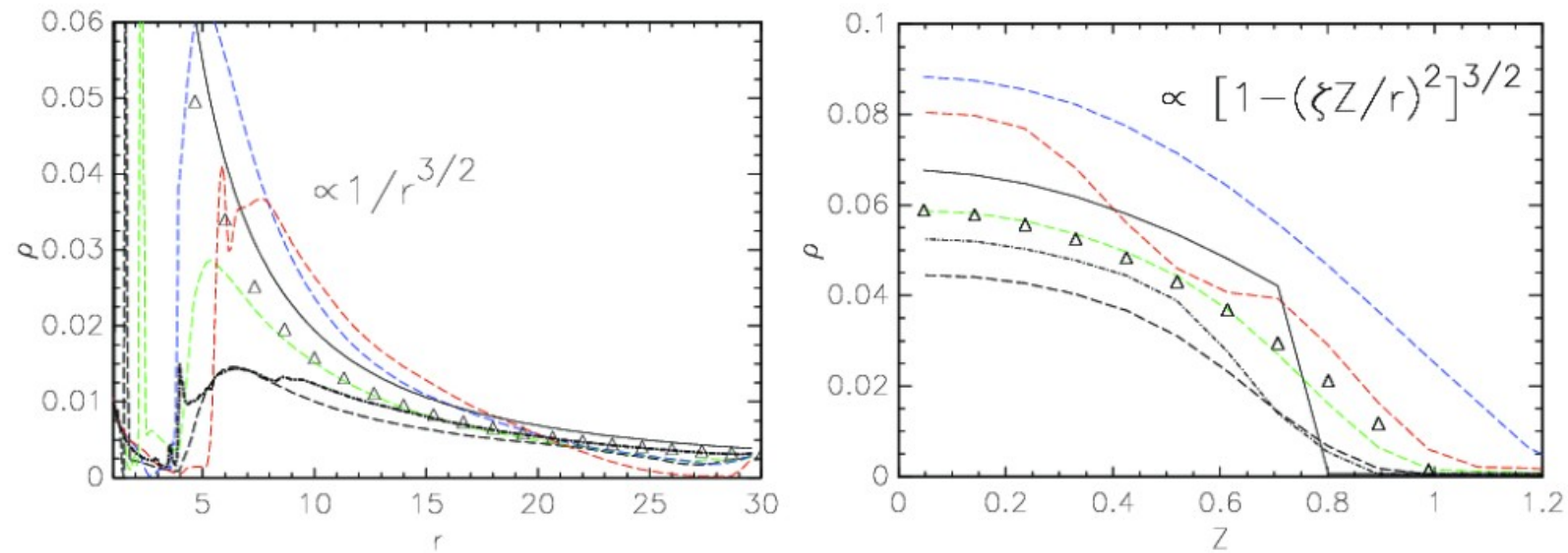
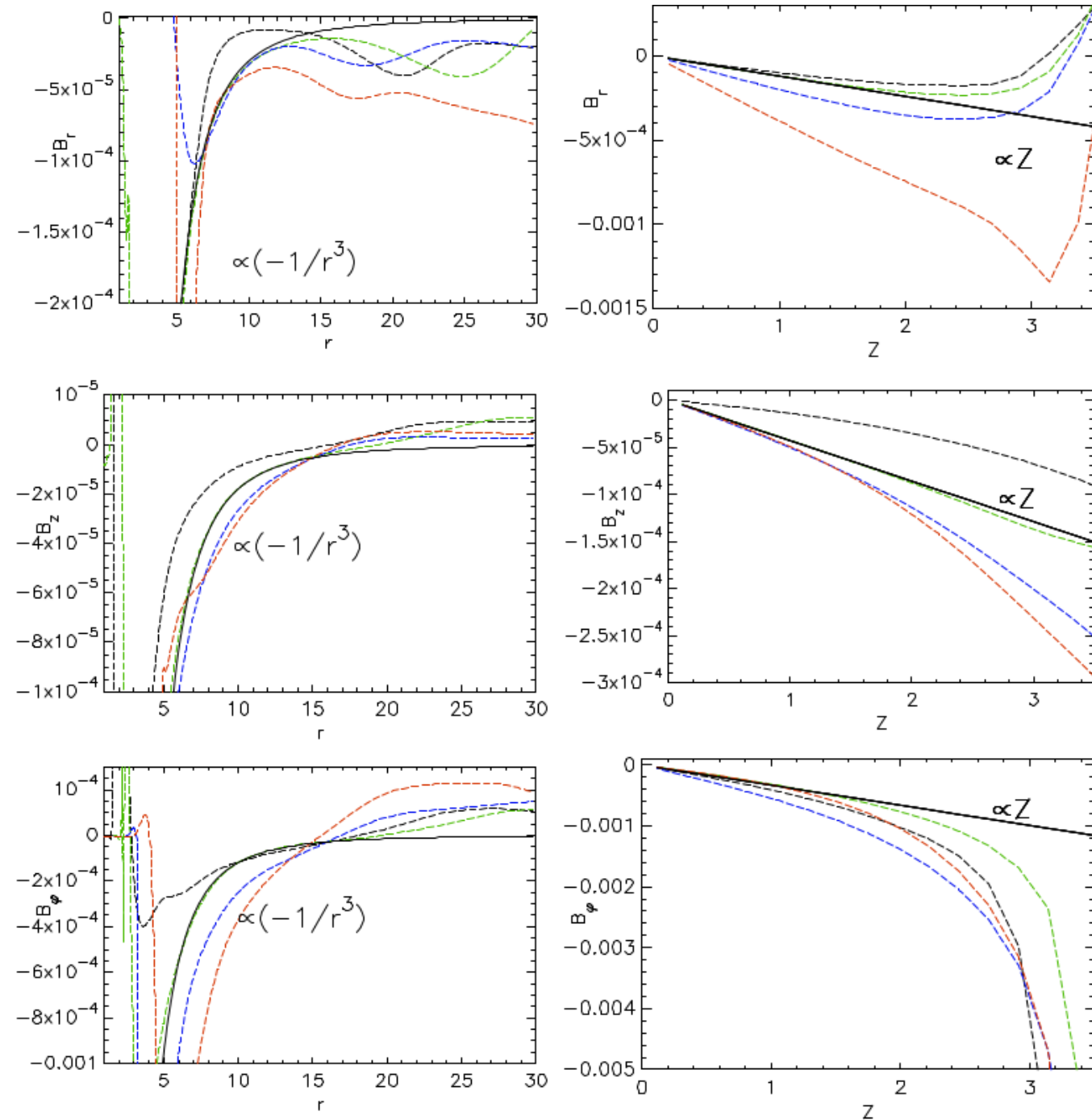


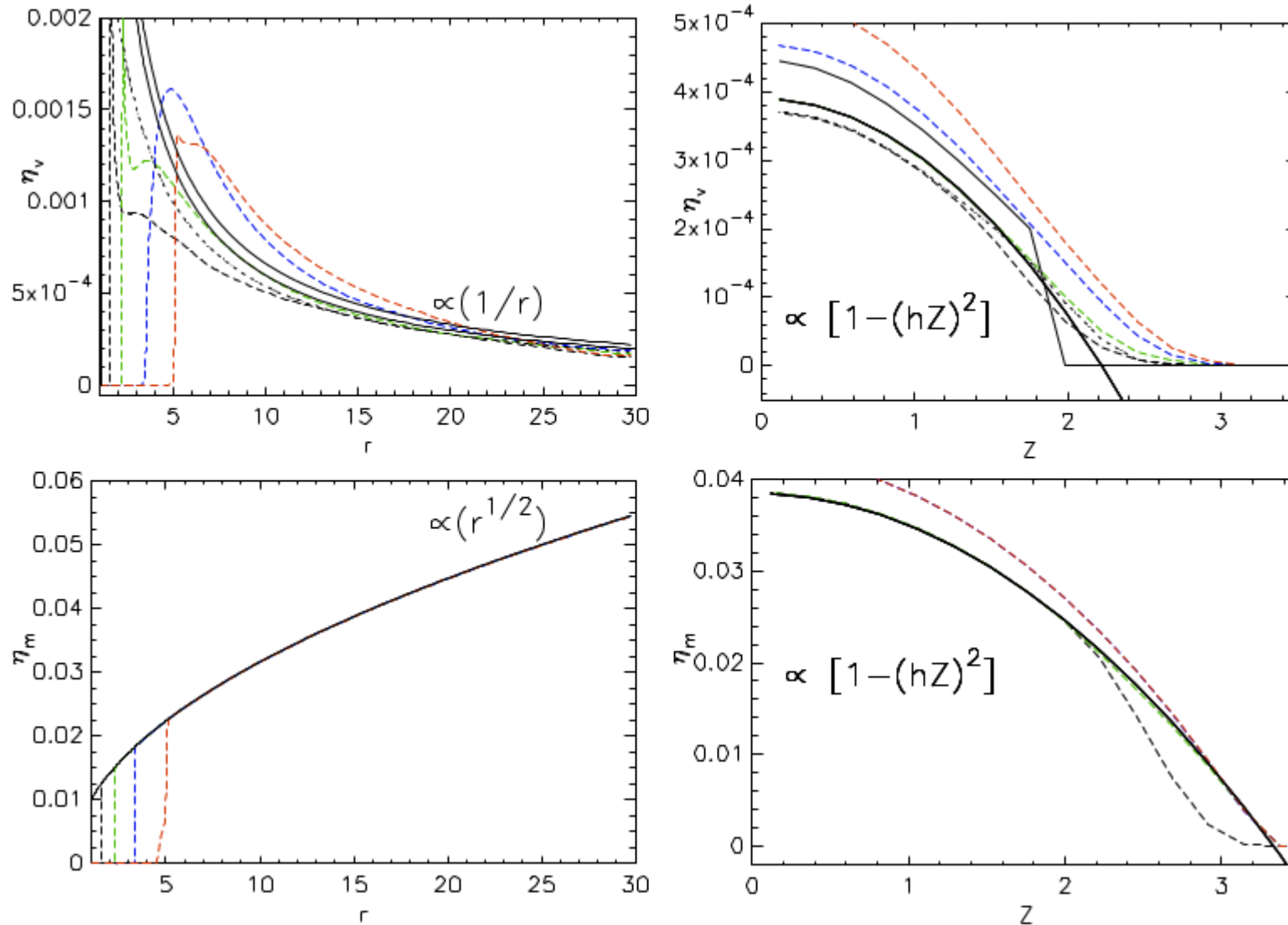
Fig. 4. Comparison of the matter density in the initial set-up (solid line) with the quasi-stationary solutions in numerical simulations in the HD (dot-dashed line) and the MHD cases. *Left panel*: along the disc surface at $\theta=83^\circ$. *Right panel*: along a vertical line at $r=6R_*$. The meaning of the lines is the same as in Fig. 3.

Comparison of SDMI simulations with increasing mag. field



Comparison for magnetic field. In black, green blue and red colors are the results in the MHD cases with the stellar magnetic field strength 0.25, 0.5, 0.75 and 1.0 kG, respectively. The closest fit to the 0.5 kG case is depicted with the thick solid line.

Trends in solutions with increasing stellar magnetic field



Comparison for diffusive coefficients. In black, green blue and red colors are the results in the MHD cases with the stellar magnetic field strength 0.25, 0.5, 0.75 and 1.0 kG, respectively. The closest fit to the 0.5 kG case is depicted with the thick solid line.

Expressions for physical quantities in the disk

We can write the results in our simulations as simple functions obtained in KK00, with coefficients of proportionality we find from our simulations:

$$\rho(r, z) = \frac{k_1}{r^{3/2}} \left[1 - \left(\zeta_1 \frac{z}{r} \right)^2 \right]^{3/2}, \quad (69)$$

$$v_r(r, z) = \frac{k_2}{r^{1/2}} \left[1 + (\zeta_2 z)^2 \right], \quad (70)$$

$$v_z(r, z) \approx \frac{z}{r} v_r(r, z) = k_3 \frac{z}{r^{3/2}} \left[1 + (\zeta_3 z)^2 \right],$$

$$v_\varphi(r, z) = \frac{k_4}{\sqrt{r}}, \quad \Omega = \frac{v_\varphi}{r} = \frac{k_4}{r^{3/2}}.$$

Magnetic field components are proportional to r^{-3} , as expected for the dipole stellar field, and depend linearly on height above the disk midplane:

$$B_r(r, z) = \frac{k_5}{r^3} z, \quad B_z(r, z) = \frac{k_6}{r^3} z, \quad B_\varphi(r, z) = \frac{k_7}{r^3} z, \quad (71)$$

$$\eta(r, z) = \frac{k_8}{r} \left[1 - \left(\zeta_8 \frac{z}{r} \right)^2 \right]^2, \quad (72)$$

$$\eta_m(r, z) = k_9 \sqrt{r} \left[1 - \left(\zeta_9 \frac{z}{r} \right)^2 \right]^{1/2}.$$

We assign the proportionality coefficients as k_1, k_2, \dots in the cases with a stellar dipole field of 500 G and 1000 G in Table 1, indicating by the additional subscripts i and o if they are given in the *inner* (R=6) or *outer* (R=15) position in the disk⁴. We also assign the corresponding coefficients ζ_1, ζ_2, \dots where needed.

In the following, we compare the above matches to solutions obtained in the simulations, with the conditions obtained from the analytical equations in the magnetic case.

Table 1. The proportionality coefficients in our simulations with $B_\star=0.5$ kG and 1 kG.

B(kG)	0.5		1	
	R=6	R=15	R=6	R=15
$k_{1i} k_{1o}$	0.9		1.2	0.29
$k_{2i} k_{2o}$	-0.01	-0.006	$+1.2 \times 10^{-4}$	-2.9×10^{-3}
k_3	-2.65×10^{-4}		-4.4×10^{-3}	-3.6×10^{-5}
k_4	0.255		0.255	
$k_{5i} k_{5o}$	-0.69	-0.41	-1.25	
$k_{6i} k_{6o}$	-0.35	-0.15	-0.29	-0.19
$k_{7i} k_{7o}$	-2.8	-1.1	-8.2	-1.18
k_8	5.8×10^{-3}		$8. \times 10^{-3}$	
k_9	0.01		0.01	
ζ_1	5.		5.	
ζ_2	0.5		0.5	
ζ_8	5.		6.8	
ζ_9	6.		4.5	

Difference between analytical expressions and numerical simulations

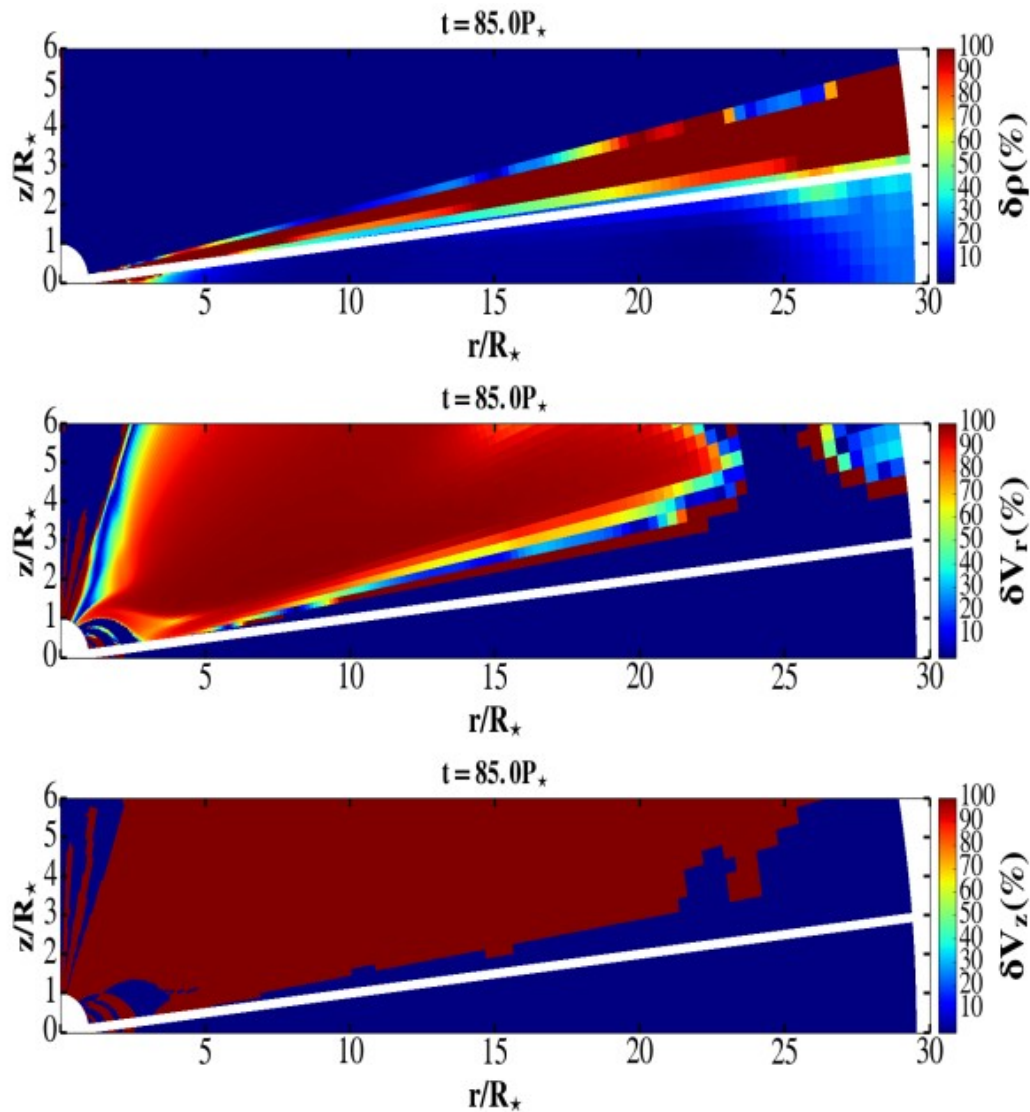
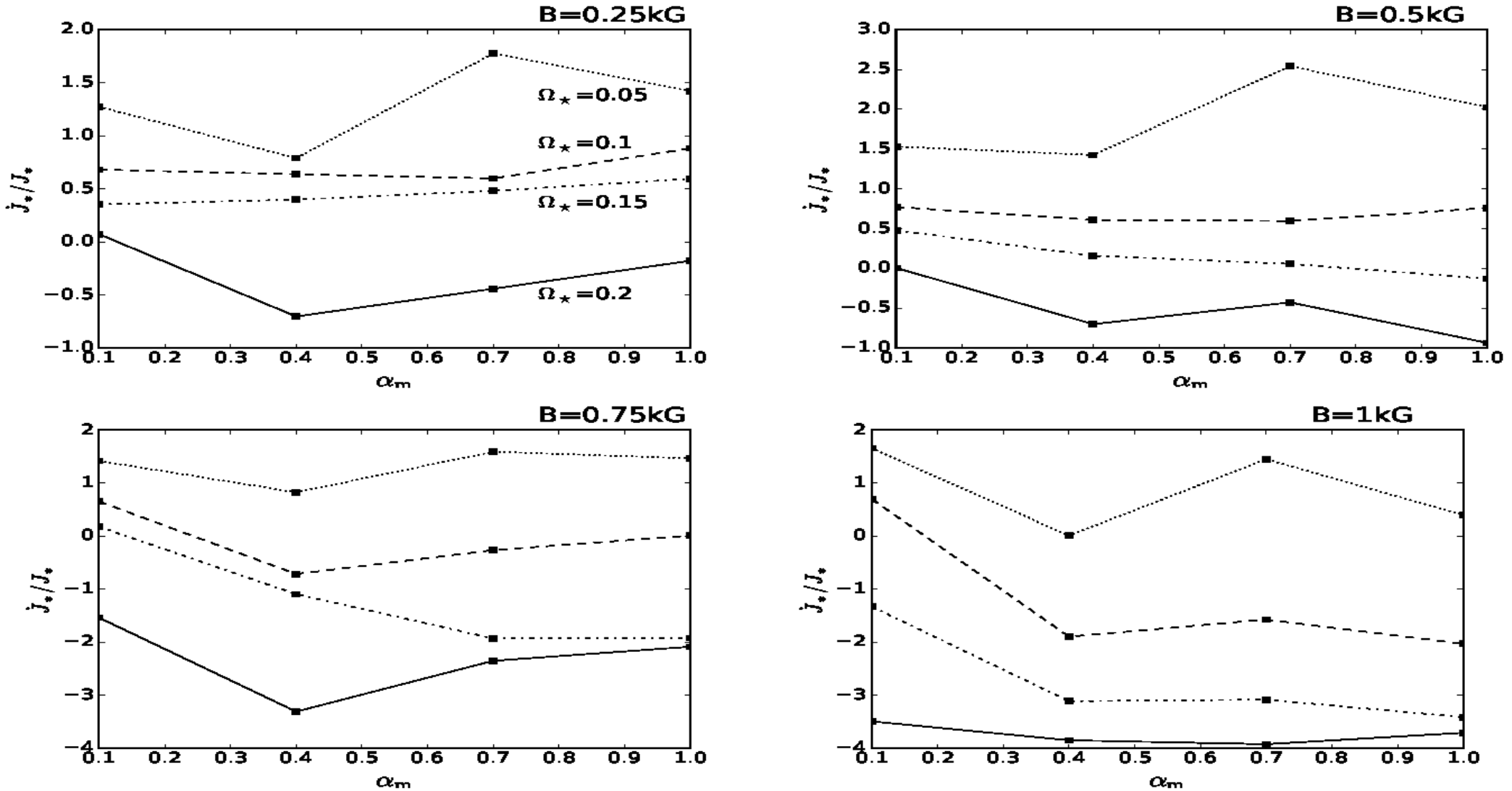


Fig. A.1. Difference between our numerical solutions and analytical expressions, in percentage of the value in the simulations. Our analytical solution is mostly inside the 10% margin everywhere inside the thin disk region, below the thick white solid line demarcating $h = 0.1r$ dependence, where h is the disk height.

Trends in angular momentum with increasing stellar magnetic field



Average angular momentum flux transported onto the stellar surface by the matter in-falling from the disk onto the star through the accretion column. In each panel is shown a set of solutions with one stellar magnetic field strength, varying the stellar rotation rate and resistivity. Positive flux spins-up the star, negative slows it down. With the increase in stellar rotation rate, spin-up of the star by the infalling matter decreases, eventually switching to the spin-down.

Trends in angular momentum

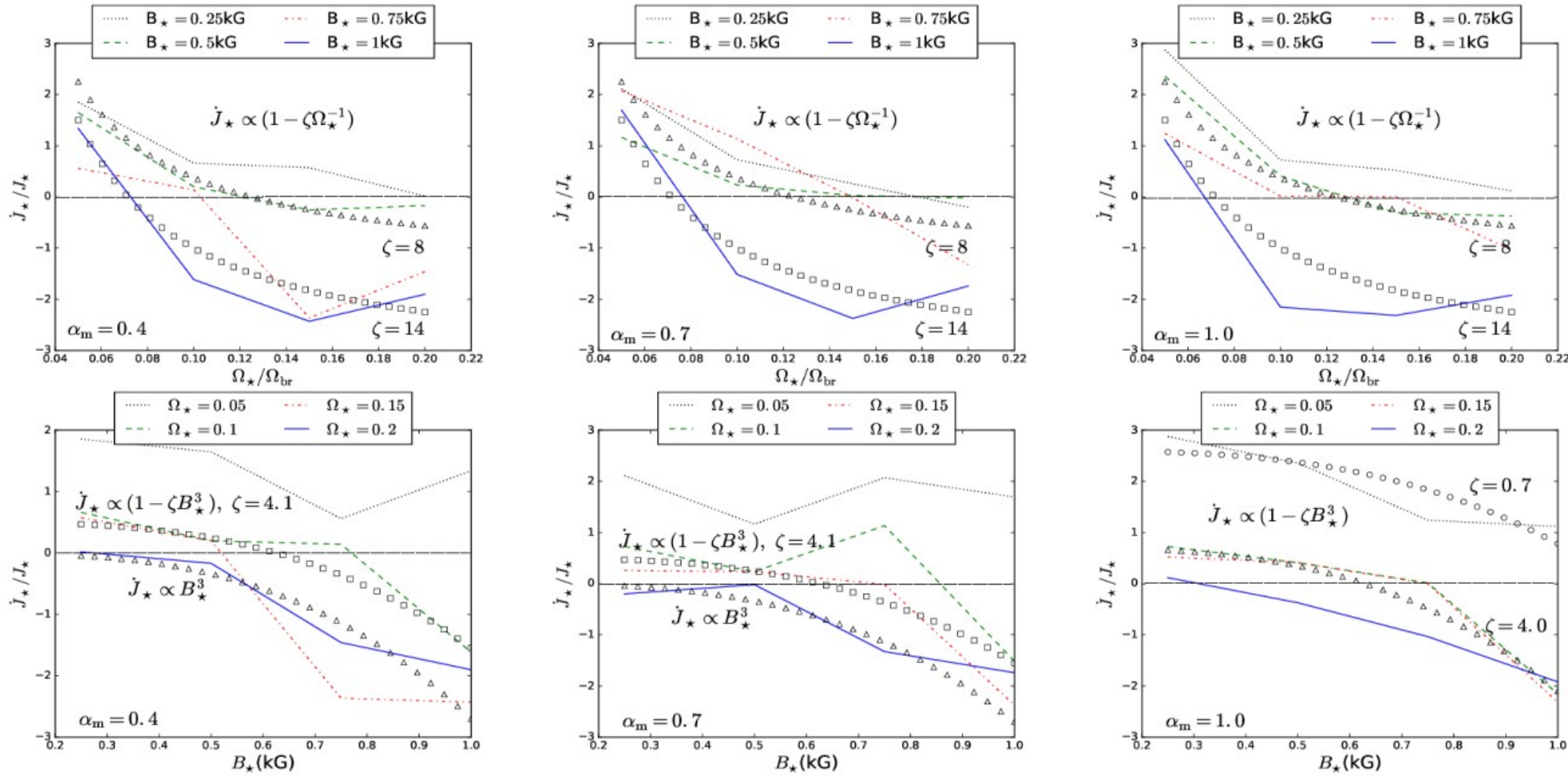
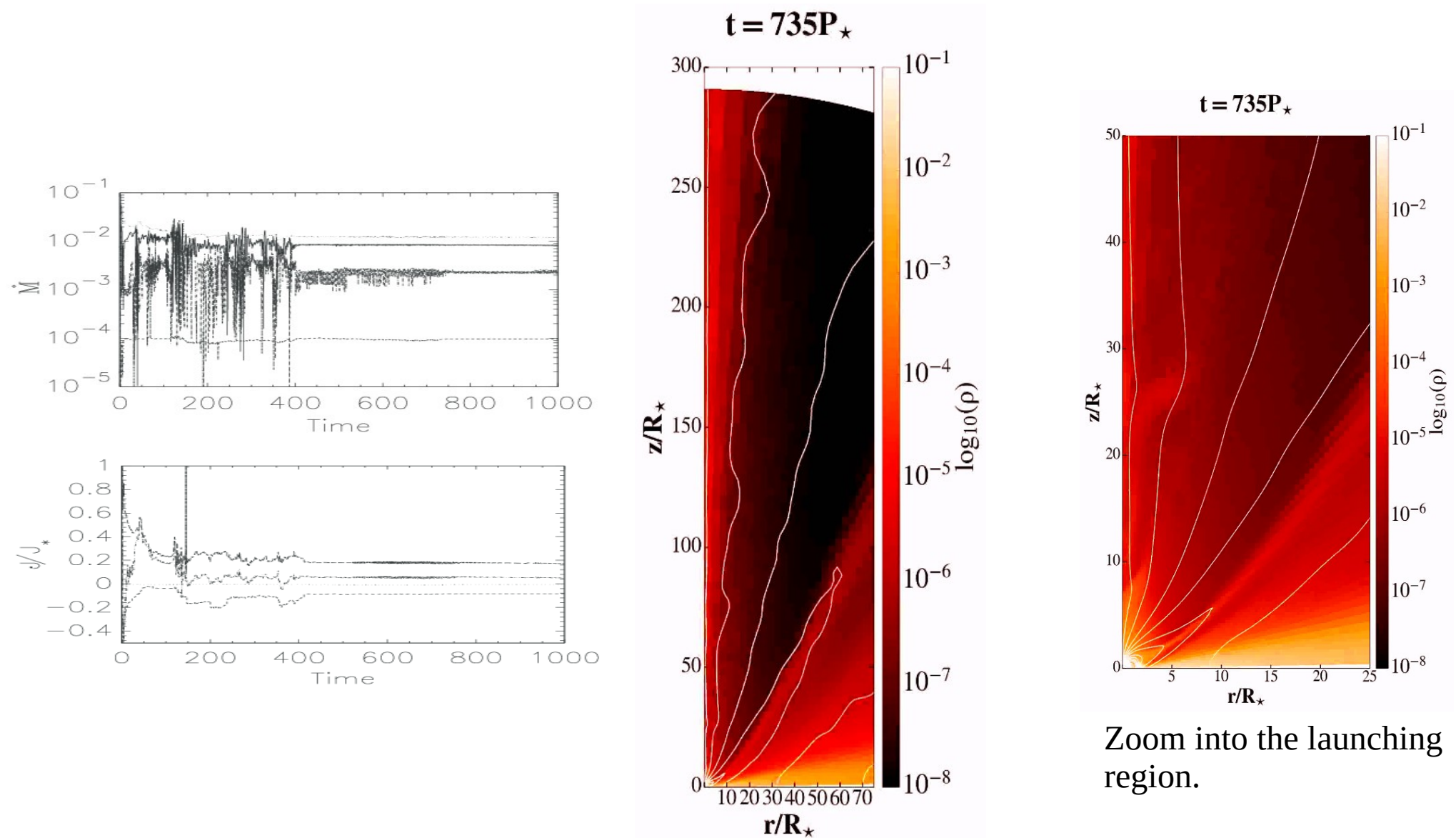


Fig. 7. Torques exerted on the star by material in-falling from the disk in all the cases without conical outflow-this are all the cases except a,b,c,d(1,5,9,13)-with the resistive coefficient $\alpha_m=0.4, 0.7$ and 1.0 . Approximate matching functions and trends in solutions with different stellar rotation rates and magnetic field strengths are shown as $\dot{J}_*(\Omega_*)$ (top panels) and $\dot{J}_*(B_*)$ (bottom panels).

Axial outflow (“jet”) launching

In the cases with faster stellar rotation, we obtain a continuous launching of an axial outflow from the star-disk magnetosphere.

The axial jet and the conical outflow are similar to the results in Romanova et al. (2009) and Zanni & Ferreira (2013).



Zoom into the launching region.

Star-disk simulations with $\alpha_v < 1$

In the cases with anomalous viscosity free parameter less than unity, there is a critical value at $\alpha_v < 0.685$. For smaller viscosity, we obtain a backflow in the midplane of the disk in our purely HD simulations:

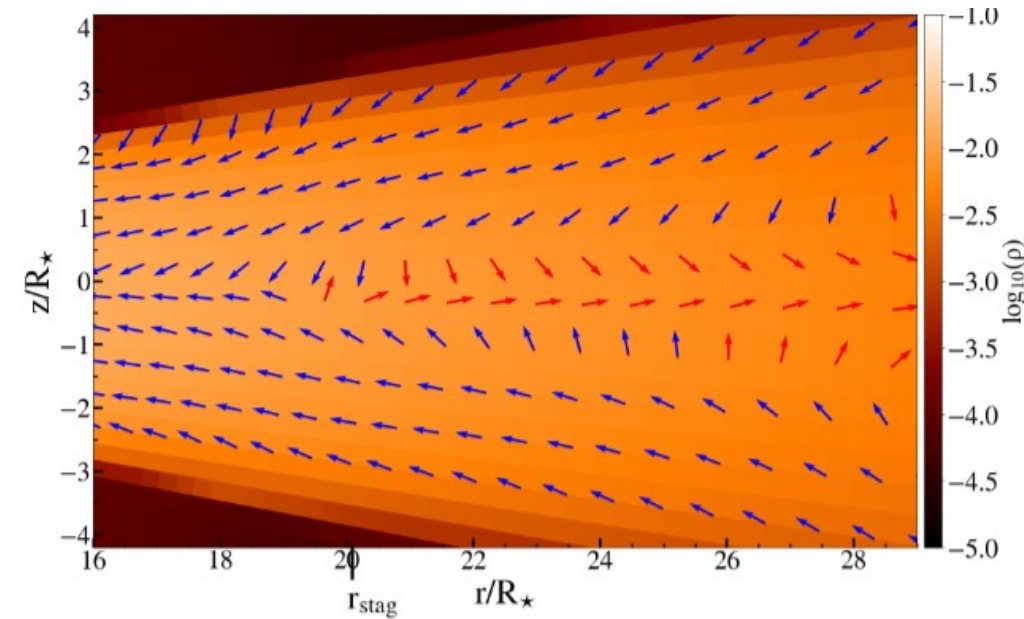


Fig. 2. A close view into a part of accretion disk in a quasi-stationary state in our purely hydrodynamic simulation with the viscous coefficient $\alpha = 0.4$. The central object is positioned at $R=0$. Analytical solution in KK00 predicts that with such a viscosity a midplane backflow should occur in the disk, in which material flows away from the central object. We confirm the backflow in our simulation. It is shown with the radial velocity vectors shown in the plot above directed from

for radial velocity in the equatorial plane is given by,

$$V_r(r, 0) = -\alpha \epsilon^2 R \left(\frac{h^2}{r^{5/2}} \right) \left[2 \left(\frac{d \ln h}{d \ln r} \right) - \Lambda \left(1 + \frac{32}{15} \alpha^2 \right) \right] \quad (1)$$

where,

$$\Lambda = \frac{11}{5} / \left(1 + \frac{64}{25} \alpha^2 \right)$$

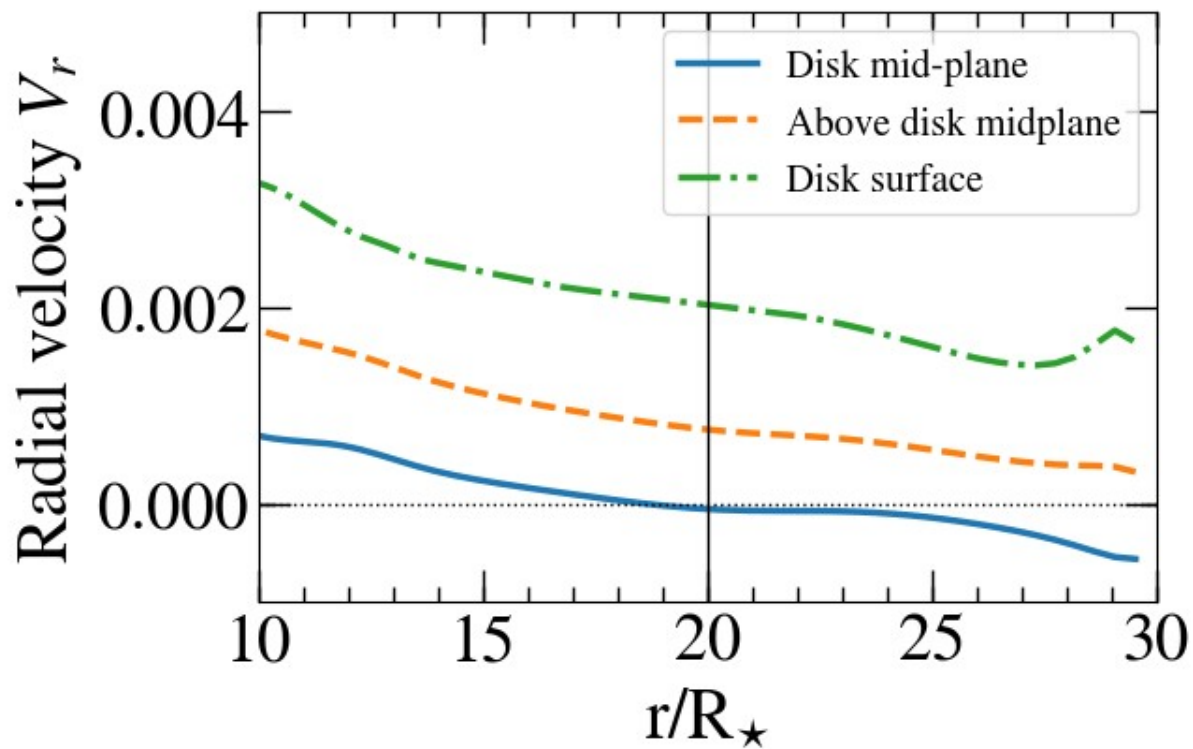
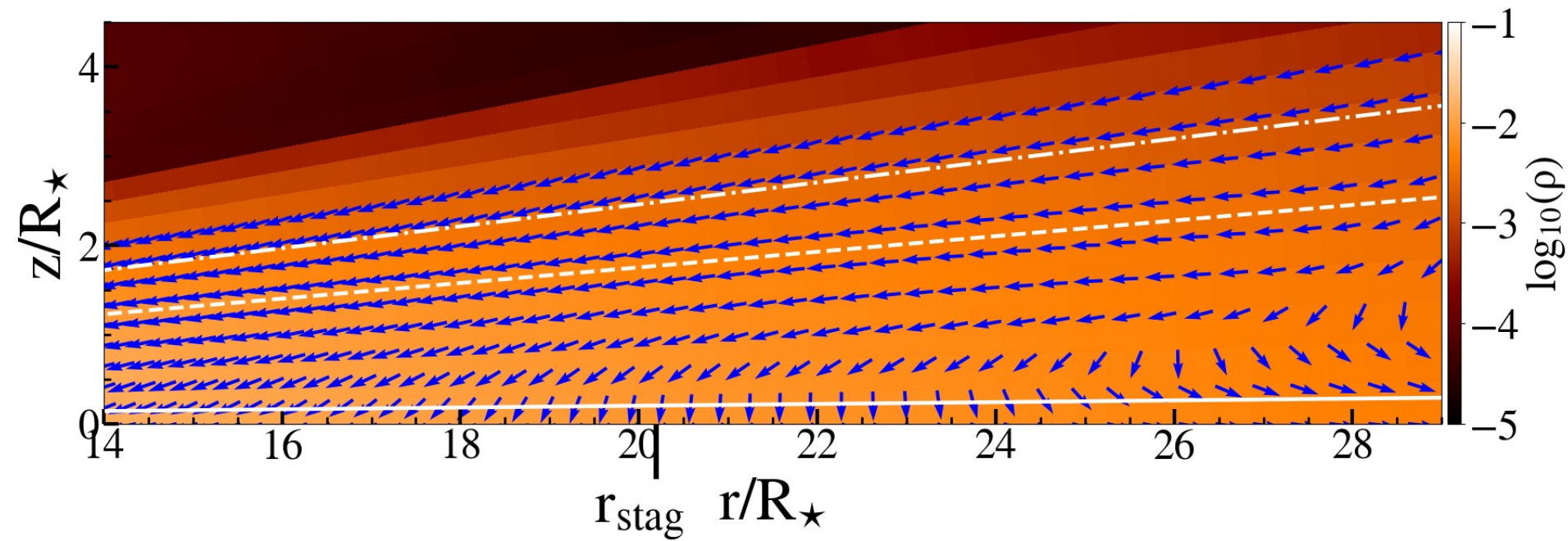
When $\alpha_v = 0$ then Λ reduces to $11/5$ and the bracketed portion of eq. (1) becomes negative, so that $V_r(r, 0) < 0$. Negative radial velocity indicates outflow in the equatorial plane away from central accretor. In the other hand when $\alpha_v = 1$ then $V_r(r, 0) > 0$ which indicates the equatorial flow is directed inwards towards the central star for all radii. The critical value over which there is no backflow is given by,

$$\alpha_{cr} \approx 0.685 \quad (2)$$

When $\alpha < \alpha_{cr}$ backflow continues all the way to infinity where the disk terminates. In the other hand when $\alpha > \alpha_{cr}$ there is no backflow in the disk. The radius for which the radial velocity is

Such a backflow could contribute to the transport of material outwards in the protoplanetary disk. This would explain the presence of crystalline dust material in the outer, cold region of the protoplanetary disk which is typically from the inner, warm region of the disk.

Star-disk magnetic simulations with $\alpha_v=0.4$



Star-disk simulations with $\alpha_v < 1$

In the magnetic cases, we also obtain midplane backflow, with a critical value at $\alpha_v < 0.6$.

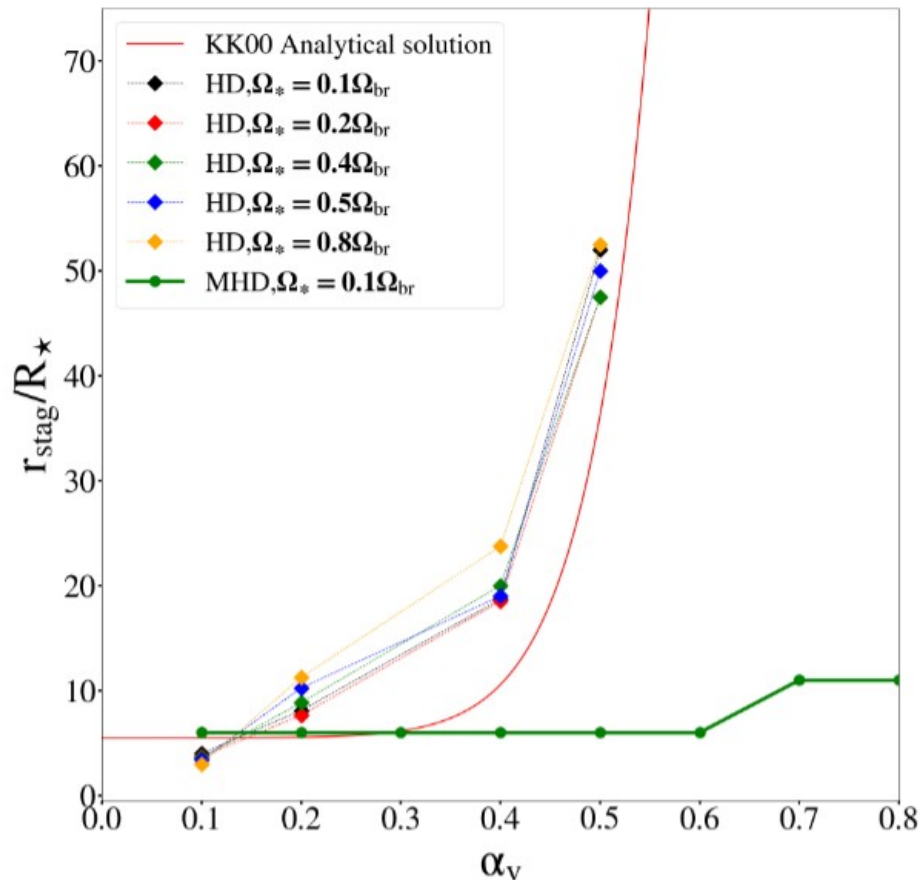
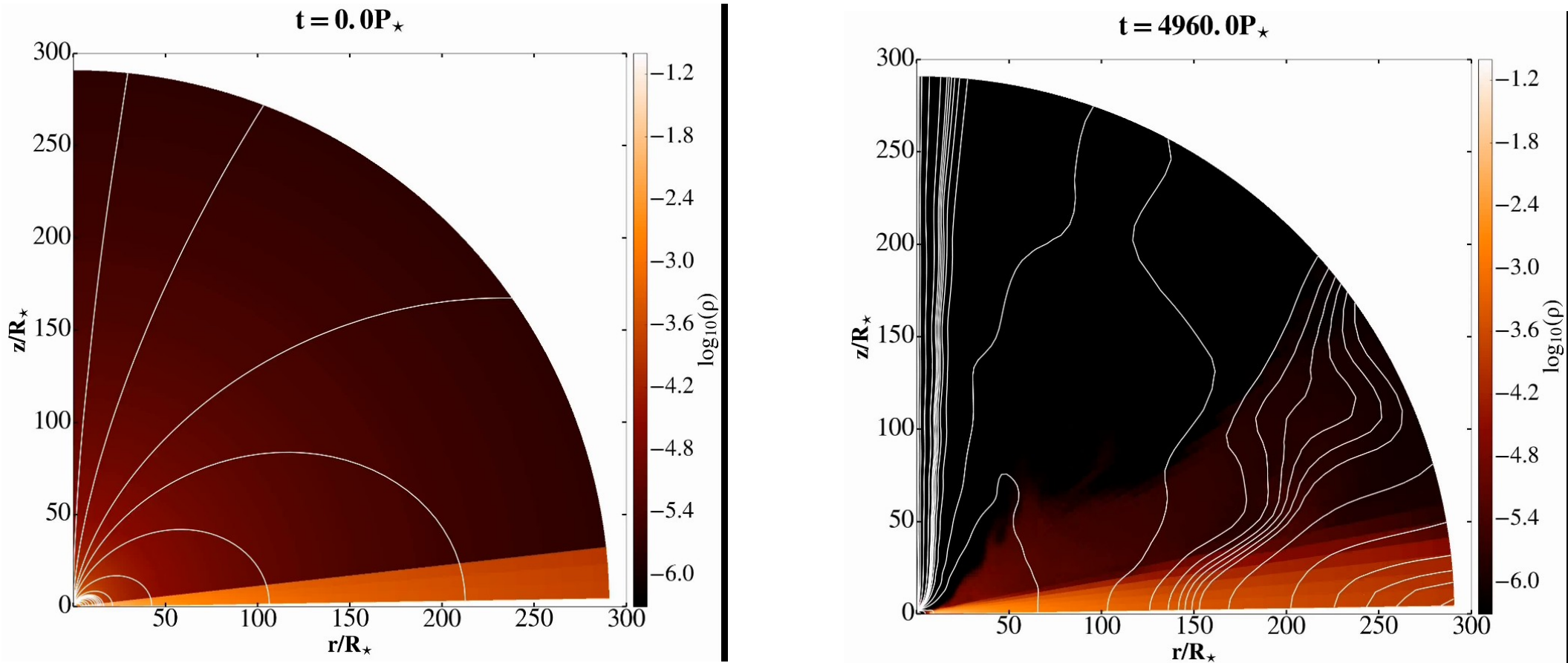


Fig. 5. Position of the stagnation radius in HD and MHD simulations with the different viscosity coefficients. The red solid curve is from the Kluzniak & Kita (2000) purely HD analytical solution.

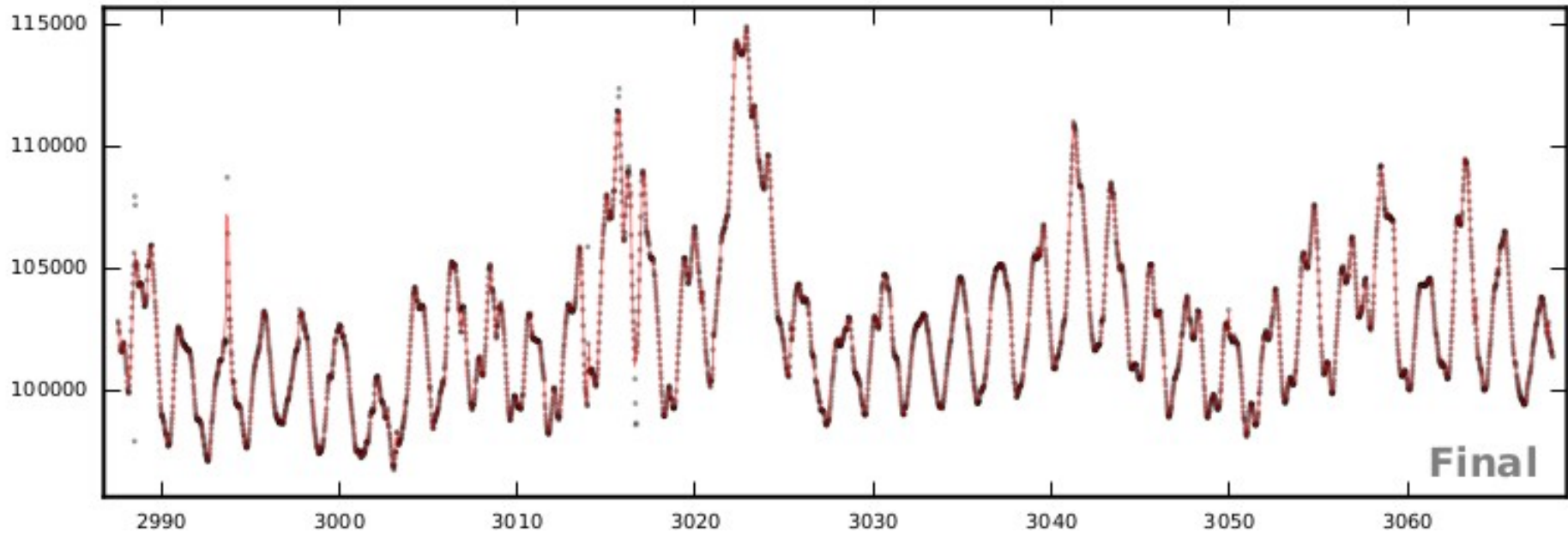
- Such a MHD solution matches the purely HD analytical solutions in 3D, where a midplane backflow is obtained with viscosity smaller than 0.685.
- Such a backflow is also reported in other simulations, with other codes and numerical methods used, and it is usually considered a numerical artifact of the initial setup.
- Recently such a backflow was reported also in simulations of a thin disc with magneto-rotational instability (MRI).
- With Ruchi Mishra, a PhD student in CAMK Warsaw, we are investigating it in our simulations.

Long lasting simulations: 5s for millisecond pulsar



This is the longest lasting simulation with star-disk magnetospheric interaction. It shows that regardless of the initial condition for the field near the origin, the large scale solution always seem to come to the one shown here in the right panel: a radially self-similar configuration, often considered as an approximation in earlier theoretical works.

Light curve hiccups-V1000 Tau



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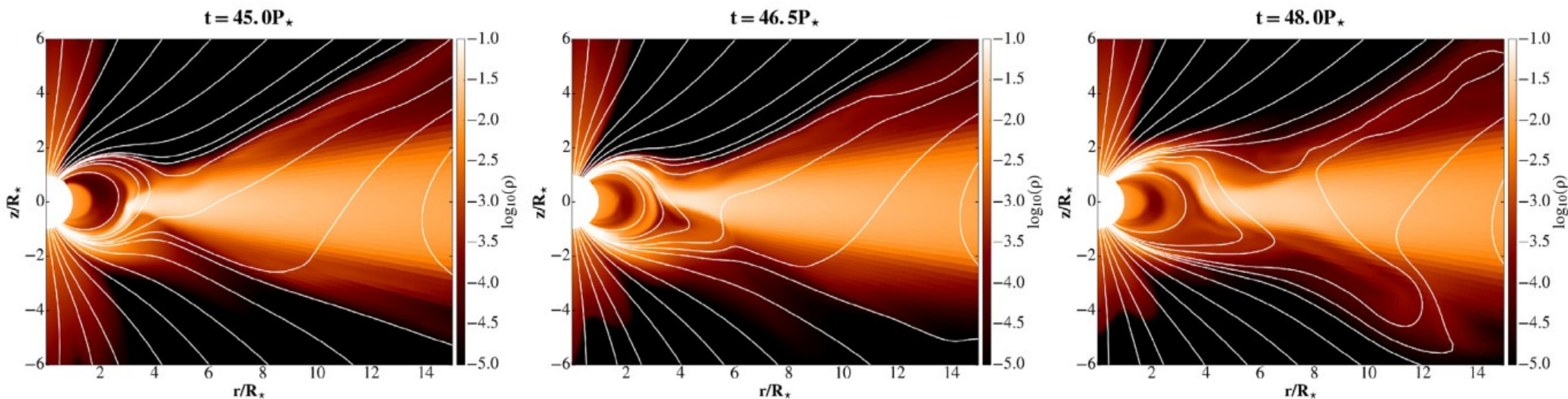


Figure 4. A sequence of snapshots from the results in the interval when switching of the accretion column from the Southern to the Northern hemisphere occurs.

Light curve hiccups

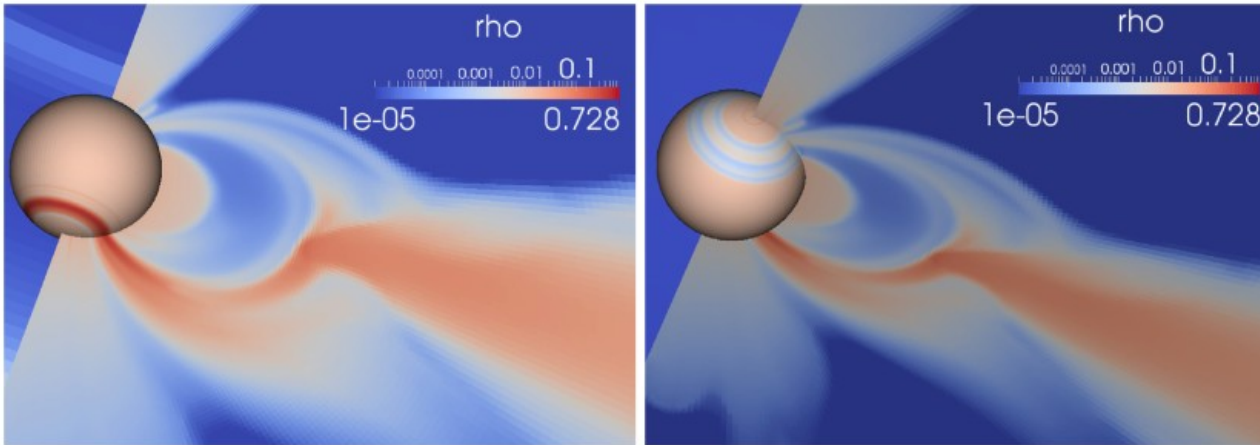
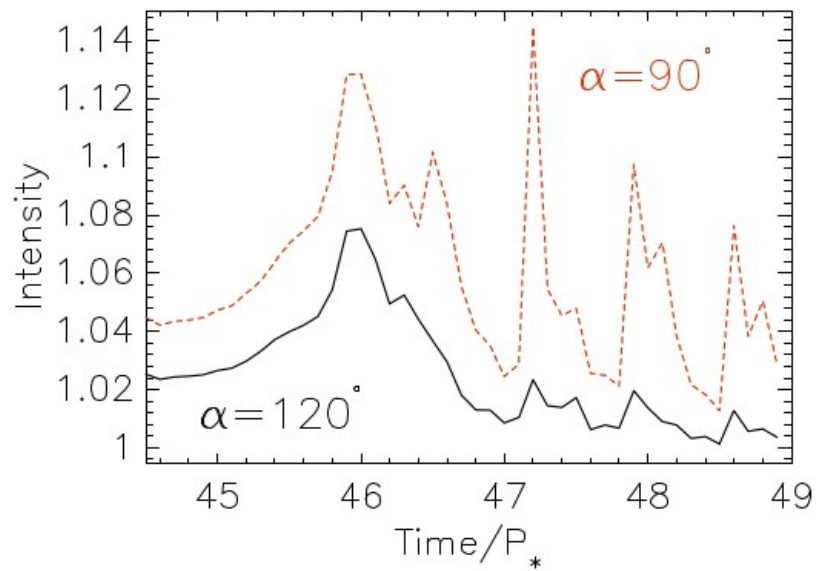
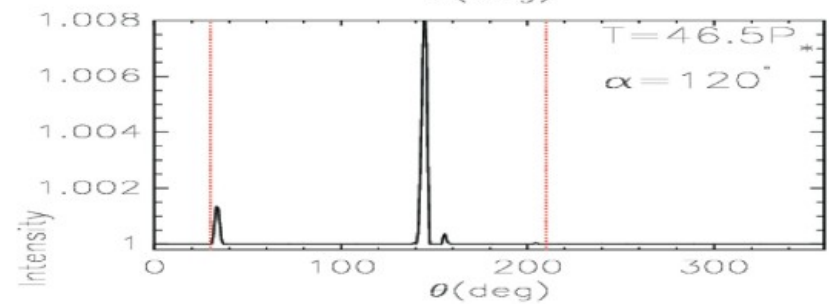
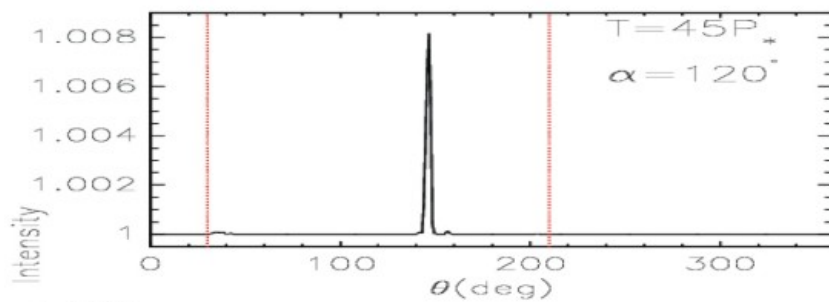


Figure 5. Snapshots in our 3D model from 2D axisymmetric simulations at $T = 45$ stellar rotations, with a cut in the meridional plane to show the accretic column and disc. In the left-hand panel is shown a view to the Southern hemisphere, with a ring-shaped hotspot at the footpoints of the accretion column. In the right-hand panel is shown a view to the Northern hemisphere, with a less dense ring-shaped hotspot than in the Southern hemisphere.



Light curve hiccups

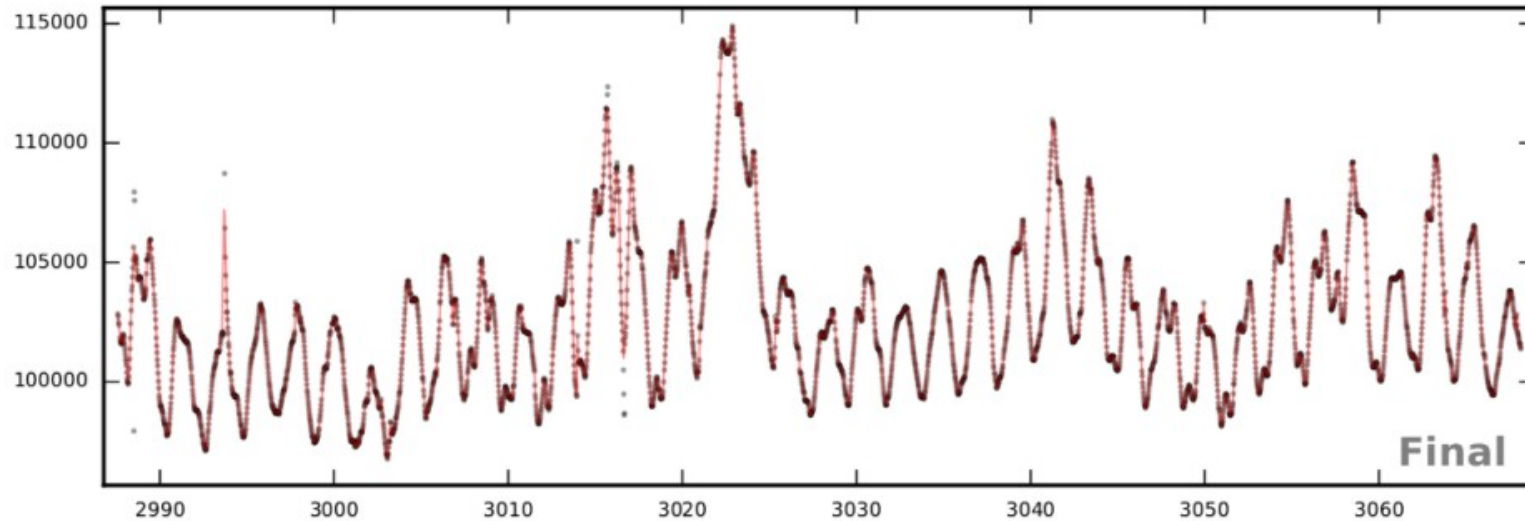
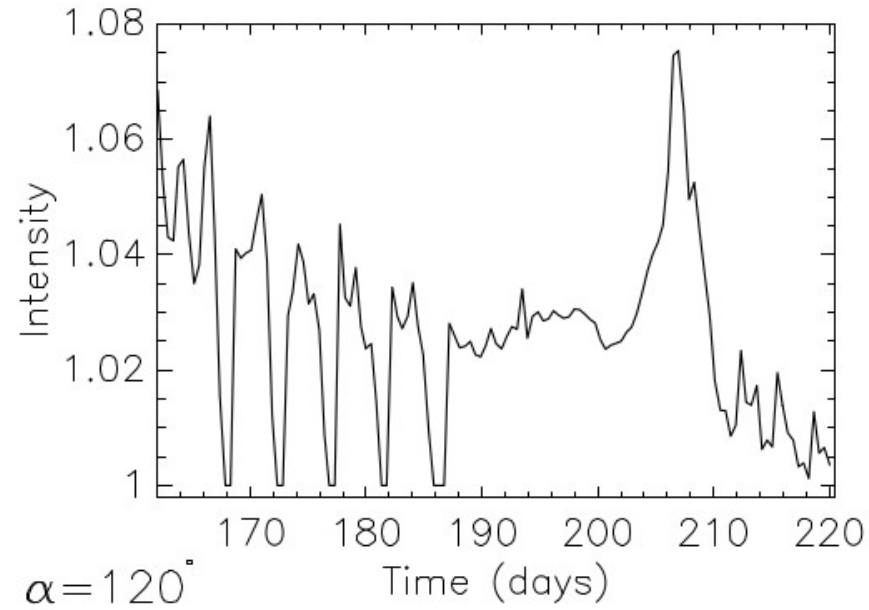
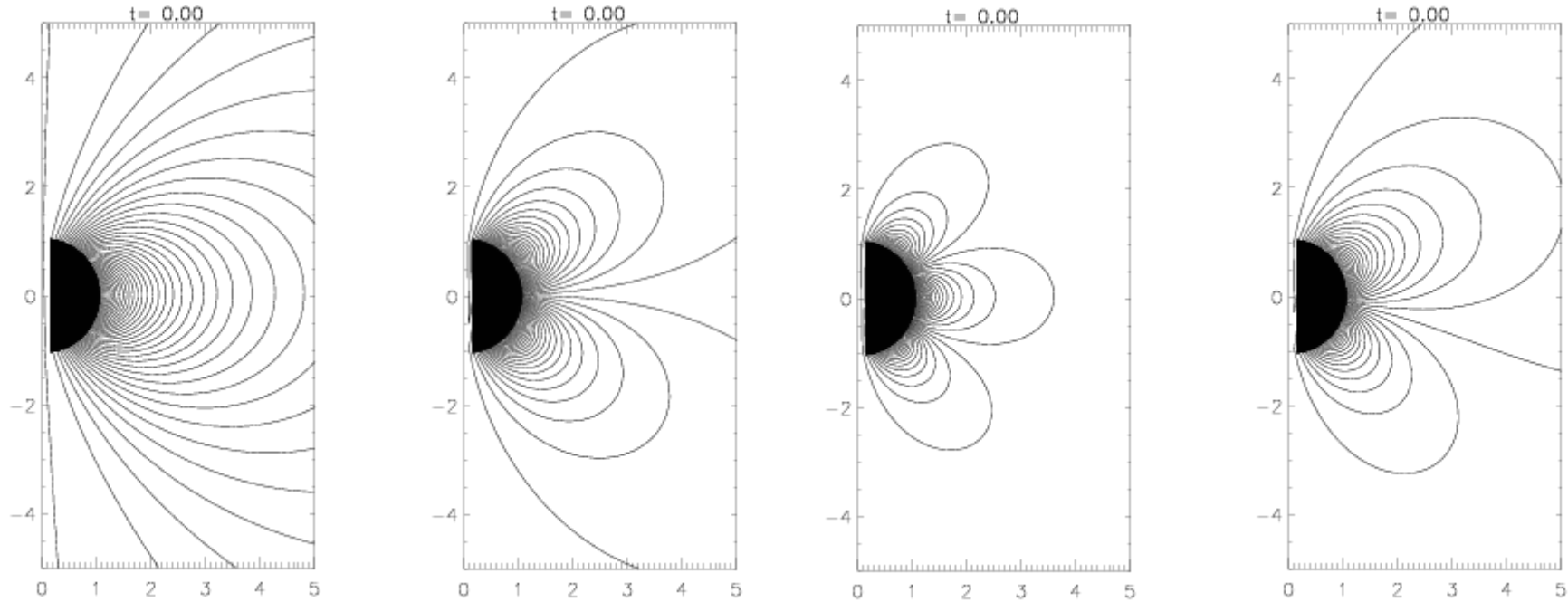


Figure 8. Top panel: intensity in a 3D model made from the longer time sequence than shown in Fig. 7. Shifts in the phase of the observed light ('hiccups') occur during the switch of the accretion column from the southern to northern stellar hemisphere between the 190 and 210 d. Bottom panel: light curve from the *Kepler* observation of V1000 Tau in which part of the contribution could occur because of the column switching. Time in the abscissa is annotated in Julian days.

Star-disk interaction with other geometries of the magnetic field



- In addition to the stellar dipole field, we also performed simulations with quadrupole, octupole and multipole fields.

Solutions with other geometries of the magnetic field

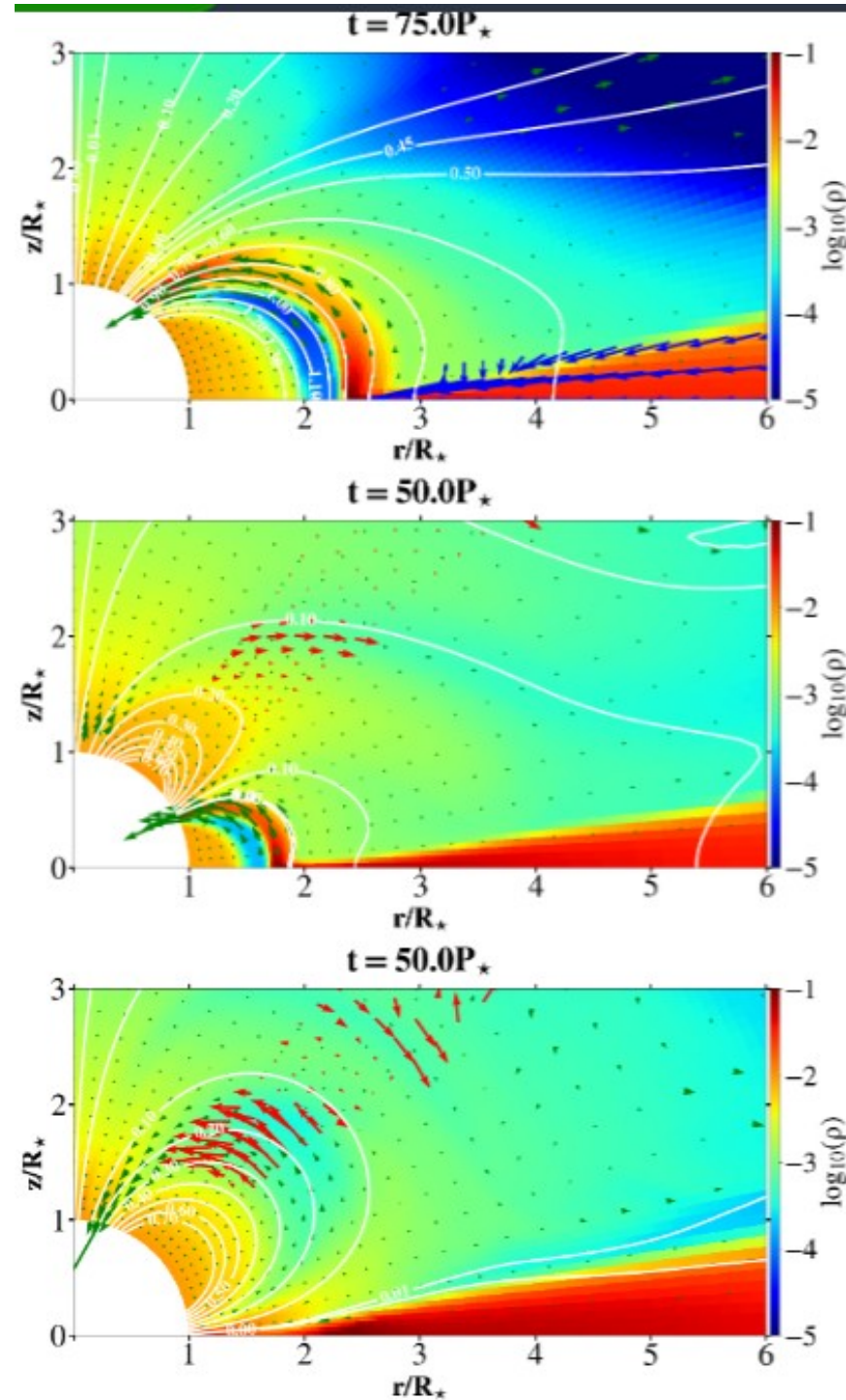
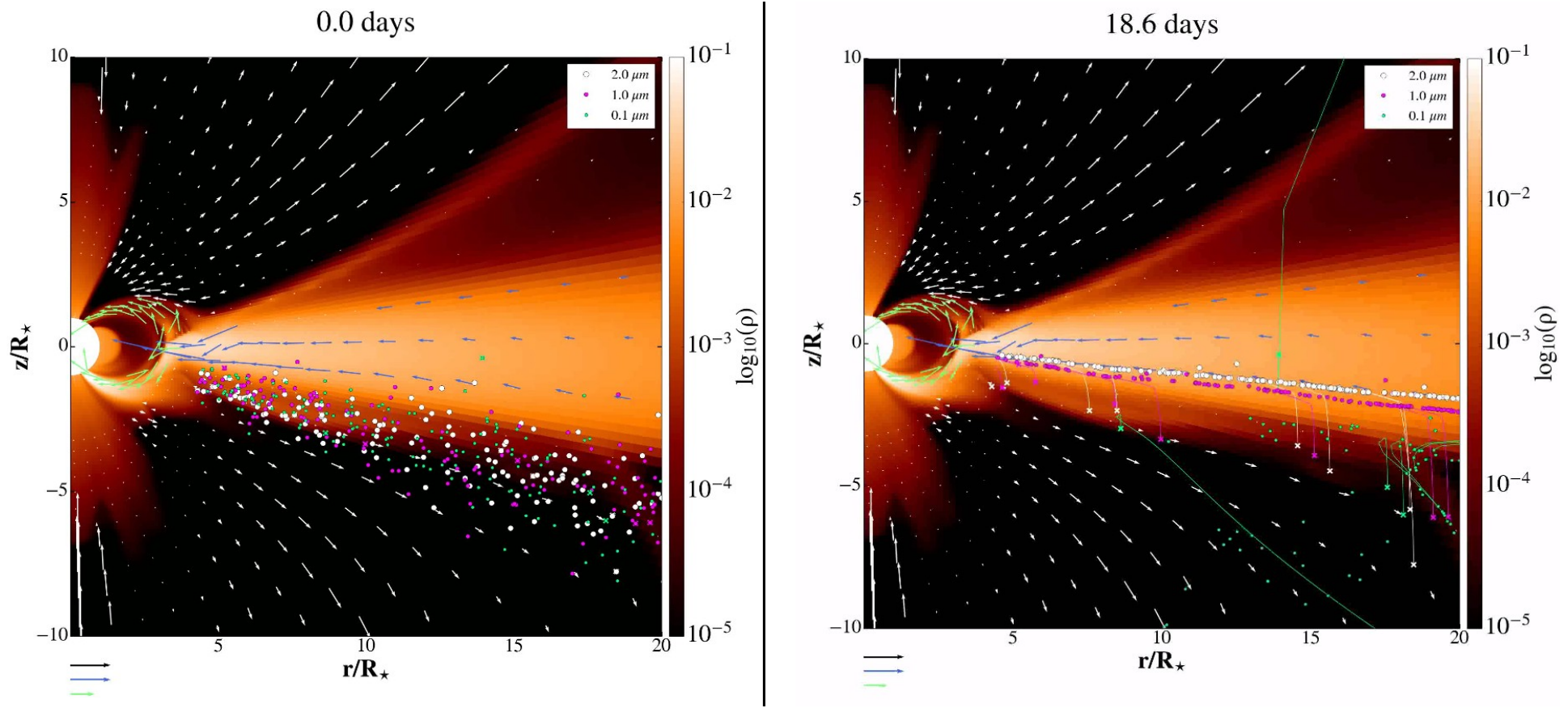


Figure: Zoom into the vicinity of the star in quasi-stationary results in our simulations with 0.5 kG stellar field, $\alpha_V = 1$, $\alpha_m = 1$ and stellar rotation rate $\Omega = 0.1\Omega_{br}$. Shown are the cases with the dipole, octupole and quadrupole stellar fields, in the top to bottom panels. The density is shown in the logarithmic color grading, poloidal magnetic field lines are shown with white solid lines, and vectors of poloidal velocity are multiplied with the factors 15 (in the disk) and 3 (in the corona) for better visibility.

Cieciuch and Cemeljic (2021, in preparation).

Post-processing of the results: the “DUSTER” code



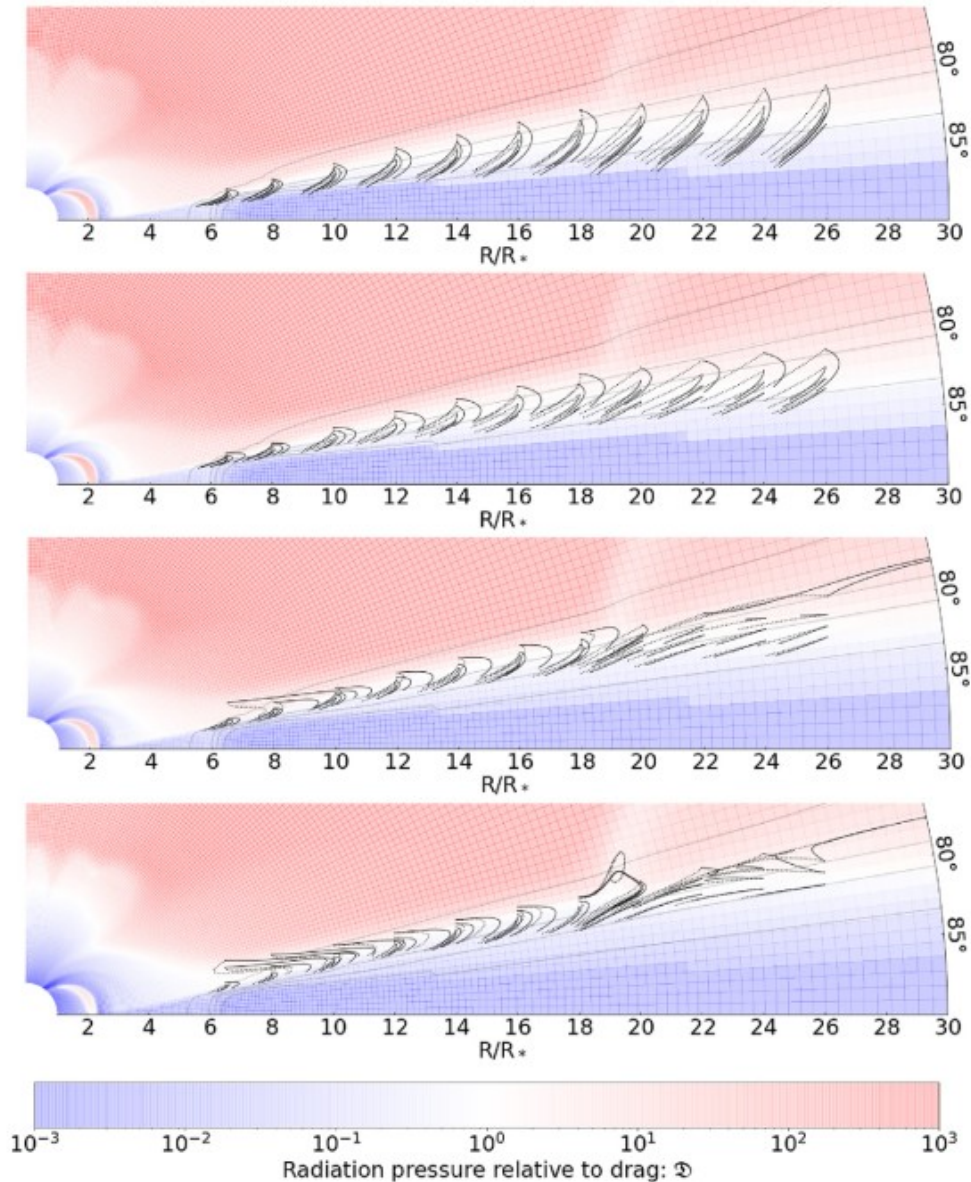
$$\ddot{\vec{r}} = -G \frac{M_{\star}}{r^3} \vec{r} - \frac{\rho_{gas}}{\rho_{gr}} \frac{c_s}{a} (\dot{\vec{r}} - \vec{v}_{gas}) + \beta G \frac{M_{\star}}{r^2}$$

$$\beta = 0.4 \frac{L_{\star}}{L_{\odot}} \frac{M_{\odot}}{M_{\star}} \frac{3000 \frac{kg}{m^3}}{\rho_{gr}} \frac{\mu m}{a}, \quad R_{in} = 0.0344 \Psi \left(\frac{1500K}{T_{gr}} \right)^2 \sqrt{\frac{L_{tot}}{L_{\odot}}} [AU],$$

With Cezary Turski, a summer student in Warsaw, we developed a Python tool “DUSTER” for post-processing of the results. In this example we work with dust grains of different cross-sections, computing grain movement in the flow with the radiation pressure on the particles included.

Post-processing of the results

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A more detailed analysis of dust grain movement under the radiation pressure was done in Vinković & Čemeljić (MNRAS, 2021). This could be helpful for the further clearing of the protoplanetary disc formation.

Figure 5. Trajectories of dust grains at different locations over the disc surface in the outflow model A. See Fig. 2 for a view of the gas velocity flow. The colour map shows the strength of radiation pressure relative to the

Summary

- The purely hydro-dynamic analytical solutions for a thin disk are available (Kita 1995 PhD Thesis, Madison Uni.; Kluzniak-Kita (arXiv 2000)).
- Viscous and resistive MHD star-disk magnetospheric interaction solutions for a thin accretion disk are available for young stellar objects. To some extent they are re-scalable to other objects with the same configuration.
 - A quasi-stationary state is obtained in a set of 64 simulations with slowly rotating stars (up to 0.2 of the breakup stellar rotation rate).
 - Results are compared to find trends for angular momentum in the solutions.
 - In the cases with $\alpha_m=0.1$, a conical outflow is launched.
 - In the cases with faster rotating stars than those in our present parameter study, an axial outflow can be launched.
- I show an example of comparison with the light curve of a young stellar object.
- We also performed simulations with other geometries of the stellar magnetic field.
- Additional results can be obtained in post-processing.

**Thank
you!**

