Optimal transient growth in keplerian discs via variational technique

V. Zhuravlev¹ D. Razdoburdin²

¹Sternberg Astronomical Institute, Moscow

²Physics Department of Moscow State University

6 September 2012



Non-modal analysis for astrophysical discs

- Basic ideas
- One application to keplerian flow
- 2 An optimization problem: common technique
 - The essence of method
 - One example: the thin ring
- An optimization through the variational formulation
 - An augmented Lagrangian and it's variation
 - Iterative scheme
 - Some preliminary results

4 Conclusions and remarks

< □ > < 同 > < 回 > < 回

Basic ideas One application to keplerian flow

Modal analysis

The linear theory of perturbation dynamics — wave and oscillations in discs, stability and transition.

The basic and traditional framework

- make an assumption of an exponential time dependence
- initial-value problem transforms to an eigenvalue problem for underlying linear dynamical operator
- usually is referred to as a modal approach or as the spectral problem assosiated with the corresponding basic flow
- gives adequate description of perturbation dynamics in case of normal operators only when eigenfuctions are orthogonal to each other
- otherwise, only describes the asymptotic $(t \to \infty)$ fate of perturbations

イロト イポト イヨト イヨト

SOR

Basic ideas One application to keplerian flow

Modal analysis

The linear theory of perturbation dynamics — wave and oscillations in discs, stability and transition.

The basic and traditional framework

- make an assumption of an exponential time dependence
- initial-value problem transforms to an eigenvalue problem for underlying linear dynamical operator
- usually is referred to as a modal approach or as the spectral problem assosiated with the corresponding basic flow
- gives adequate description of perturbation dynamics in case of normal operators only when eigenfuctions are orthogonal to each other
- otherwise, only describes the asymptotic $(t \to \infty)$ fate of perturbations

$$\mathbf{A}\mathbf{A}^{\dagger} = \mathbf{A}^{\dagger}\mathbf{A}, \quad \mathbf{A}\mathbf{x} = \lambda\mathbf{x}$$

イロト イポト イヨト イヨト

Non-modal analysis

Basic ideas One application to keplerian flow

The existence of a non-zero shear in the flow makes dynamical operator non-normal and eigenfuctions become non-orthogonal making possible the transient growth of perturbations at finite time intervals.

Schmid (2007)



DQ P

Non-modal analysis

Basic ideas One application to keplerian flow

The existence of a non-zero shear in the flow makes dynamical operator non-normal and eigenfuctions become non-orthogonal making possible the transient growth of perturbations at finite time intervals.

Schmid (2007)



Non-modal analysis for astrophysical discs

An optimization problem: common technique An optimization through the variational formulation Conclusions and remarks

Basic ideas One application to keplerian flow

Non-modal analysis

An example: the plane Poiseuille flow

Schmid (2007)



nac

I

Non-modal analysis for astrophysical discs

An optimization problem: common technique An optimization through the variational formulation Conclusions and remarks

Non-modal analysis

Basic ideas One application to keplerian flow

An example: the plane Poiseuille flow

Schmid (2007)

$$\mathbf{A}^{\dagger}\mathbf{A}\,\mathbf{v} = \sigma^2\,\mathbf{v}$$
$$\mathbf{A}\mathbf{A}^{\dagger}\,\mathbf{u} = \sigma^2\,\mathbf{u}$$

The singular values of A are the eigenvalues of AA^{\dagger} and $A^{\dagger}A$



< ロ > < 同 > < 回 > < 回 >

Non-modal analysis

Basic ideas One application to keplerian flow

Modal analysis	\Rightarrow	arrang eigenv
Non-modal analysis	\Rightarrow	arrang singula

arrange eigenmodes according to their eigenvalues // timespan independent

arrange singular vectors according to their singular values // for each timespan

(日)

Non-modal analysis

Basic ideas One application to keplerian flow

Modal analysis	\Rightarrow	arrange eigenmodes according to their eigenvalues // <u>timespan independent</u>
Non-modal analysis	\implies	arrange singular vectors according to their singular values // for each timespan

The system of singular vectors of non-normal operator is *orthogonal and complete* just like the system of eigen-vectors of the hermitian operator

To find optimal perturbations means to find the <u>highest</u> singular value and corresponding singular vector.

Basic ideas One application to keplerian flow

Transient activity of keplerian accretion flow

Optimal global perturbations.

Ioannou & Kakouris (2001) — studied 2D rotating flow with a keplerian rotation constructed of a viscous incompressible fluid. Calculated initial optimal perturbations and the statistical steady state of the flow under an external stochastic forcing.





<ロト <同ト < ヨト < ヨト

Basic ideas One application to keplerian flow

Transient activity of keplerian accretion flow

Optimal global perturbations.

Ioannou & Kakouris (2001)

The shape of optimal perturbation

The shape of the leading component of the flow response to an external stochastic forcing

< □ > < 同 > < 回 > < 回





Basic ideas One application to keplerian flow

Transient activity of keplerian accretion flow

Optimal global perturbations.

But what will get if consider an almost keplerian hypersonic thin disc?

What will be the picture when involve a sonic wave-like perturbations?

Basic ideas One application to keplerian flow

Transient activity of keplerian accretion flow

Optimal global perturbations.

But what will get if consider an almost keplerian hypersonic thin disc?

What will be the picture when involve a sonic wave-like perturbations?

The determination of optimal perturbation in such a complex flow can be addressed using two different mathematical descriptions

(日)

DQ (P

The essence of method One example: the thin ring

Optimization: using the spectral solutions

Henningson & Schmid (2001)

Consider a linear subspace S_N of the solutions

$$q = \sum_{n=1}^{N} \kappa_n \tilde{q}_n$$

with the basis $\tilde{q}_n = \{ \bar{v}_r, \bar{v}_{\varphi}, \bar{h} \}_n \times e^{im\varphi} = \{ \tilde{q}^1, \tilde{q}^2, \tilde{q}^3 \}_n \times e^{im\varphi}$ where $\{ \bar{v}_r, \bar{v}_{\varphi}, \bar{h} \}_n$ are the profiles constituting the Fourier-amplitudes

are the profiles constituting the Fourier-amplitudes of *n* eigen-mode.

(We assume the baratropic case)

$$\boldsymbol{\kappa} = \boldsymbol{e}^{\boldsymbol{\Lambda} t} \boldsymbol{\kappa}^{0}$$
$$\boldsymbol{\kappa}^{0} = (\kappa_{1}^{0}, \kappa_{2}^{0}, ..., \kappa_{N}^{0})^{T}$$
$$\boldsymbol{\kappa} = (\kappa_{1}, \kappa_{2}, ..., \kappa_{N})^{T}$$

$$\mathbf{\Lambda} = diag\{-i\omega_1, -i\omega_2, ..., -i\omega_N\}$$

(日)

DQ (P

In that way the coordinates of q in S_N are

$$\kappa_n(t) = \kappa_n^0 e^{-i\omega_n t}$$

The essence of method One example: the thin ring

Optimization: using the spectral solutions

The Metrics

Let us measure perturbation by its total acoustic energy

$$E_{a} = \frac{1}{2} \int \rho \left(\delta v_{r}^{2} + \delta v_{\varphi}^{2} + n \frac{\delta h^{2}}{h_{eq}} \right) r dr \, dz \, d\varphi$$

So introduce the inner product in the following way

$$(f,g) = \pi \int_{r_1}^{r_2} \rho \left[f^{1*}g^1 + f^{2*}g^2 + \frac{n}{h_{eq}}f^{3*}g^3 \right] r dr \, dz$$

And the norm of the arbitrary perturbation is

$$(q,q) = E_a = \|\kappa\|^2 = \sum_{i,j=1}^N \kappa_i^* \kappa_j M_{ij} = \kappa^{\dagger} \mathbf{M} \kappa$$

with metrics in S_N defined as $M_{ij} = (\tilde{q}_i, \tilde{q}_j)$

(日)

DQ (P

The essence of method One example: the thin ring

Optimization: using the spectral solutions

The optimal growth

• The growth factor is

$$g(t) = \frac{\|\boldsymbol{\kappa}(t)\|^2}{\|\boldsymbol{\kappa}^0\|^2} = \frac{\|\boldsymbol{e}^{\boldsymbol{\Lambda} t} \boldsymbol{\kappa}^0\|^2}{\|\boldsymbol{\kappa}^0\|^2}$$

• The optimal growth is

$$G(T) = \max_{\mathcal{K}^0 \neq 0} g(T) \equiv \| e^{\mathbf{\Lambda} T} \|^2 = \| \mathbf{F} e^{\mathbf{\Lambda} T} \mathbf{F}^{-1} \|_2^2 = \sigma_1^2 \left(\mathbf{F} e^{\mathbf{\Lambda} T} \mathbf{F}^{-1} \right)$$

where $\mathbf{M} = \mathbf{F}^{\dagger} \mathbf{F}$ is Cholesky decomposition and

 σ_1 is the first singular value of the corresponding matrix

SVD decomposition gives σ₁ & **v**₁

 $\kappa^0 = \mathbf{F}^{-1} \mathbf{v}_1$ is the initial unit vector that corresponds to perturbation that attains the largest possible energy growth *G* at the moment *T*

・ ロ ト ・ 一 早 ト ・ 日 ト

DQ (P

The essence of method One example: the thin ring

Approach discs: the thin ring

- Let us take the baratropic torus constructed of perfect fluid rotating with a $\Omega \sim r^{-q}$ in an external Newtonian potential.
- This model case was extensively studied in 1980's as a subject to Papaloizou-Pringle instability.
- Consider the case $q \rightarrow 3/2$, i.e. the thin quasi-keplerian torus with $\delta = H/r \ll 1$.

Take the most trivial part of the spectrum — using WKBJ method calculate modes ~ exp(-iωt + imφ),
 (i) with no dependence on z,
 (ii) with corotation radius beyond the outer boundary of torus.



イロト イポト イラト イラ

DQ P

The essence of method One example: the thin ring

The result of optimization

Optimal growth curves for the linear combination of neutral acoustic modes with dimension N = 20 and parameters $x_d = 1.0$, m = 25, n = 3/2.



- Sonic time scale $t_s \sim (\delta \Omega_0)^{-1}$ ۲
- Magnitude of $G \sim \delta^{-(...)}$

MQ P

The essence of method One example: the thin ring

The result of optimization

Evolution of the particular optimal combination of neutral acoustic modes.

Left panel

The instant angular momentum flux density alternating with time

Right panel

The growth of the total acoustic energy

DQ (P

An augmented Lagrangian and it's variation Iterative scheme Some preliminary results

Optimization: method of Lagrange multipliers

The goal is to determine the maximum of the following cost Lagrangian

$$\mathcal{J} = \frac{\|\mathbf{q}(\tau)\|^2}{\|\mathbf{q}(0)\|^2}$$

 Method of Lagrange multipliers gives an augmented Lagrangian (the Lagrange multipliers here — q̃ and q̃₀ which are the adjoint variables)

$$\mathcal{L}(\mathbf{q},\tilde{\mathbf{q}},\mathbf{q}_{0},\tilde{\mathbf{q}}_{0}) = \mathcal{J} - \int_{0}^{\tau} (\,\tilde{\mathbf{q}}\,,\dot{\mathbf{q}} - \mathbf{A}\mathbf{q}\,)\,dt - (\,\tilde{\mathbf{q}}_{0}\,,\mathbf{q}(\mathbf{0}) - \mathbf{q}_{0}\,)$$

- $\bullet~$ The zero variations of ${\cal L}$ over the corresponding quantities give
 - 1) over the $\mathbf{q} \mapsto$ the direct dynamical equations
 - 2) over the $\tilde{\mathbf{q}} \mapsto$ the adjoint equations
 - 3) over the $\mathbf{q}_{\mathbf{0}} \mapsto$ the relationship between $\mathbf{q}(\tau)$ and $\tilde{\mathbf{q}}(\tau)$
 - 4) over the $\tilde{\mathbf{q}}_0 \mapsto$ the relationship between $\mathbf{q}(0)$ and $\tilde{\mathbf{q}}(0)$

・ロト ・ 同ト ・ ヨト ・ ヨト

SOR

An augmented Lagrangian and it's variation Iterative scheme Some preliminary results

Direct and adjoint system of equations

$$\mathbf{q} = \{\delta \mathbf{v}_r, \delta \mathbf{v}_\varphi, \delta \mathbf{v}_z, \delta \mathbf{p}\}$$

$$\dot{\mathbf{q}} = \mathbf{A} \mathbf{q}$$

 $\dot{\tilde{\mathbf{q}}} = -\mathbf{A}^{\dagger} \tilde{\mathbf{q}}$

$$\mathbf{A} = \begin{pmatrix} -im\Omega & 2\Omega & 0 & \frac{1}{\rho} \left(\frac{\rho, r}{\rho} - \frac{\partial}{\partial r} \right) \\ -\frac{\kappa^2}{2\Omega} & -im\Omega & 0 & -\frac{im}{r\rho} \\ 0 & 0 & -im\Omega & \frac{1}{\rho} \left(\frac{\rho, z}{\rho} - \frac{\partial}{\partial z} \right) \\ -\rho a^2 \left(\frac{1}{r} + \frac{\rho, r}{\rho} + \frac{\partial}{\partial r} \right) & -\frac{im}{r} \rho a^2 & -\rho a^2 \left(\frac{\rho, z}{\rho} + \frac{\partial}{\partial z} \right) & -im\Omega \end{pmatrix}$$
$$\mathbf{A}^{\dagger} = \begin{pmatrix} im\Omega & -\frac{\kappa^2}{2\Omega} & 0 & -\frac{1}{\rho} \left(\frac{\rho, r}{\rho} - \frac{\partial}{\partial r} \right) \\ 2\Omega & im\Omega & 0 & \frac{im}{r\rho} \\ 0 & 0 & im\Omega & -\frac{1}{\rho} \left(\frac{\rho, z}{\rho} - \frac{\partial}{\partial z} \right) \\ \rho a^2 \left(\frac{1}{r} + \frac{\rho, r}{\rho} + \frac{\partial}{\partial r} \right) & \frac{im}{r} \rho a^2 & \rho a^2 \left(\frac{\rho, z}{\rho} + \frac{\partial}{\partial z} \right) & im\Omega \end{pmatrix}$$

<ロト < 団 > < 臣 > < 臣 > -

DQC2

3

An augmented Lagrangian and it's variation Iterative scheme Some preliminary results

Iterative scheme

The straightforward way to find the solution to variational problem described above is the following iterative scheme



イロト イポト イヨト イヨト

An augmented Lagrangian and it's variation Iterative scheme Some preliminary results

Iterative scheme

The straightforward way to find the solution to variational problem described above is the following iterative scheme



The iterative scheme above is equivalent to iteration $\mathbf{q}_{n+1} = \mathbf{U} \cdot \mathbf{q}_n$, where $\mathbf{U} = e^{(\mathbf{A}^{\dagger} + \mathbf{A}) t}$ is a hermitian positive operator.

・ロト ・ 同ト ・ ヨト ・ ヨト

DQ (P

An augmented Lagrangian and it's variation Iterative scheme Some preliminary results

Convergence of iterative scheme

Conversion of two different arbirary initial perturbations into the unique optimal initial perturbation corresponding to a particular timespan.

Left panel

The instant shapes

Right panel

The instant values of energy growth

(日)

DQ P

An augmented Lagrangian and it's variation Iterative scheme Some preliminary results

Evolution of optimal perturbation

Comparative evolution of any arbitrary initial profile and optimal initial profile seen on the previous slide

Left panel

The instant shapes

Right panel

The instant values of energy growth.

Blue curve represents the optimal growth which is the highest possible energy enhancement at each point.

(日)

DQ P

An augmented Lagrangian and it's variation Iterative scheme Some preliminary results

Variational technique: the advantages

- Don't need spectral solutions anymore (no issues with corotational and Lindblad resonances of modes, continuous spectra, unbounded flows etc)
- Don't need any kind of matrix representation for dynamical operator (profit in numerical resourses)
- Viscous and other additional terms can be straightforwardly added into the underlying cauchy problem
- The determination of optimal perturbations can be easily extended to the non-stationary flows (i.e. transient dynamics in the non-stationary accretion discs)
- Finally, the variational technique can be employed in the domain of the non-linear perturbations

(日)

SOR

Conclusions

- A global non-modal approach to a hypersonic polytropic flow with free boundaries and a nearly keplerian rotation was attempted
- Two different methods of optimization were employed,

 i) the one involving the decomposition of perturbations over the spectral solutions (i.e. over the modes)
 ii) the one with variational formulation that requires the advance of direct and adjoint cauchy problems
- The advantages of the latter method were discussed briefly
- It was revealed that in quasikeplerian tori the certain (optimal) combinations of the neutral sonic modes with corotation radius beyond the outer boundary can exhibit a considerable transient growth at the sonic timescale.
- Keplerian disc also has a potential to drive a global transient dynamics.

<ロト <同ト < ヨト < ヨト

Possible developments

- Include the vertical motions in the perturbed flow.
- Include the viscosity and consider the accreting flows.
- Solve the problem of the stochastic forcing of thin accretion disc.

イロト イポト イヨト イヨト

= nar

Thank you for your attention

What astrophysical applications could it have?..

< D > < P > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D > < D

nac

3